

# **NXB0108PWJ Datasheet**





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DiGi Electronics Part Number NXB0108PWJ-DG

> Manufacturer Nexperia USA Inc.

Manufacturer Product Number NXB0108PWJ

> Description IC TRANSLATOR BIDIR 20TSSOP

**Detailed Description** Voltage Level Translator Bidirectional 1 Circuit 8 Ch

annel 110Mbps 20-TSSOP



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## **Purchase and inquiry**

Manufacturer Product Number:	Manufacturer:
NXB0108PWJ	Nexperia USA Inc.
Series:	Product Status:
	Active
Translator Type:	Channel Type:
Voltage Level	Bidirectional
Number of Circuits:	Channels per Circuit:
1	8
Voltage - VCCA:	Voltage - VCCB:
1.2 V ~ 3.6 V	1.65 V ~ 5.5 V
Input Signal:	Output Signal:
Output Type:	Data Rate:
Tri-State	110Mbps
Operating Temperature:	Features:
-40°C ~ 125°C (TA)	
Mounting Type:	Package / Case:
Surface Mount	20-TSSOP (0.173", 4.40mm Width)
Supplier Device Package:	Base Product Number:
20-TSSOP	NXB0108

## **Environmental & Export classification**

RoHS Status:	Moisture Sensitivity Level (MSL):
ROHS3 Compliant	1 (Unlimited)
REACH Status:	ECCN:
REACH Unaffected	EAR99
HTSUS:	
8542.39.0001	

## **NXB0108**

## Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 2.1 — 31 July 2024

**Product data sheet** 

## 1. General description

The NXB0108 is an 8-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 8-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.2 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 1.65 V and 5.5 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

#### 2. Features and benefits

- · Wide supply voltage range:
  - $V_{CC(A)}$ : 1.2 V to 3.6 V and  $V_{CC(B)}$ : 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2500 V for A port
  - HBM: ANSI/ESDA/JEDEC JS-001 class 3B exceeds 15000 V for B port
  - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

## 3. Ordering information

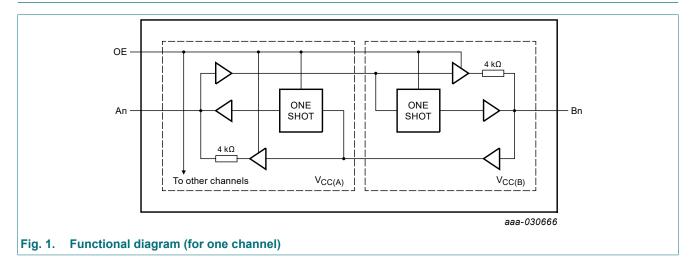
**Table 1. Ordering information** 

Type number	Package								
	Temperature range	Name	Description	Version					
NXB0108PW	-40 °C to +125 °C	TSSOP20	plastic thin shrink small outline package; 20 leads; body width 4.4 mm	SOT360-1					
NXB0108BQ	-40 °C to +125 °C	DHVQFN20	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 20 terminals; body 2.5 × 4.5 × 0.85 mm	SOT764-1					



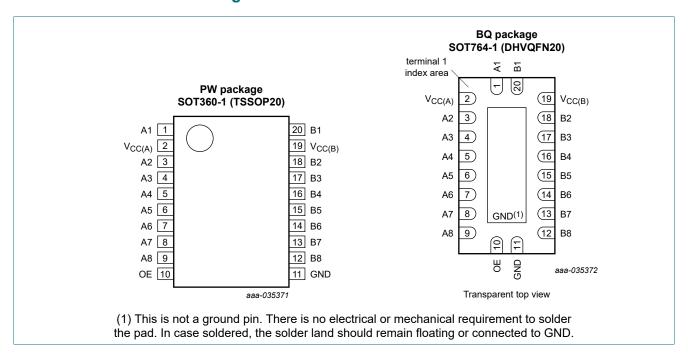
#### Dual supply translating transceiver; auto direction sensing; 3-state

## 4. Functional diagram



## 5. Pinning information

### 5.1. Pinning



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#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
A1, A2, A3, A4, A5, A6, A7, A8	1, 3, 4, 5, 6, 7, 8, 9	data input or output (referenced to V <sub>CC(A)</sub> )
V <sub>CC(A)</sub>	2	supply voltage A
OE	10	output enable input (active HIGH; referenced to $V_{\text{CC(A)}}$ )
GND	11	ground (0 V)
B1, B2, B3, B4, B5, B6, B7, B8	20, 18, 17, 16, 15, 14, 13, 12	data input or output (referenced to V <sub>CC(B)</sub> )
V <sub>CC(B)</sub>	19	supply voltage B

## 6. Functional description

#### Table 3. Function table

 $H = HIGH \text{ voltage level}; L = LOW \text{ voltage level}; X = don't care; Z = high-impedance OFF-state.}$ 

Supply voltage		Input	Input/output		
$V_{CC(A)}$ $V_{CC(B)}$		OE	An	Bn	
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	L	Z	Z	
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	input or output	output or input	
GND[1]	GND[1]	Х	Z	Z	

<sup>[1]</sup> When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

## 7. Limiting values

#### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+6.5	V
VI	input voltage		[1]	-0.5	+6.5	V
Vo	output voltage	Active mode	[1][2][3]	-0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	[1]	-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V		-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2]	-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +125 °C	[4]	-	500	mW

<sup>1]</sup> The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

<sup>[2]</sup> V<sub>CCO</sub> is the supply voltage associated with the output.

<sup>[3]</sup>  $V_{CCO}$  + 0.5 V should not exceed 6.5 V.

<sup>[4]</sup> For SOT360-1 (TSSOP20) package: P<sub>tot</sub> derates linearly with 10.0 mW/K above 100 °C. For SOT764-1 (DHVQFN20) package: P<sub>tot</sub> derates linearly with 12.9 mW/K above 111 °C.

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 8. Recommended operating conditions

Table 5. Recommended operating conditions [1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
Vo	output voltage	Power-down or 3-state mode; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	40	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CCI</sub> or both at GND.

### 9. Static characteristics

#### **Table 6. Typical static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = -20 \mu\text{A}$	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = 20 \mu\text{A}$	-	0.09	-	V
I <sub>I</sub>	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V to } V_{CCO}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; [1] $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; $V_I$ or $V_O$ = 0 V to 3.6 V; $V_{CC(A)}$ = 0 V; $V_{CC(B)}$ = 0 V to 5.5 V	-	-	±1	μΑ
		B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V	-	-	- - ±1 ±1	μΑ
C <sub>I</sub>	input capacitance	OE input; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	5	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	5	-	pF
	capacitance	B port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	8	-	pF

<sup>[1]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

<sup>[2]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 7. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>										
	1.8 V		1.8 V		2.5	2.5 V		3.3 V		5.0 V	
	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>									
1.2 V	10	10	10	10	10	20	10	1050	nA		
1.5 V	10	10	10	10	10	10	10	650	nA		
1.8 V	10	10	10	10	10	10	10	350	nA		
2.5 V	-	-	10	10	10	10	10	40	nA		
3.3 V	-	-	-	-	10	10	10	10	nA		

#### **Table 8. Static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Parameter Conditions		-40 °C to	o +85 °C	-40 °C to	Unit	
				Min	Max	Min	Max	1
V <sub>IH</sub>	HIGH-level	A or B port and OE input	[1]					
	input voltage	V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
V <sub>IL</sub>	LOW-level	A or B port and OE input	[1]					
	input voltage	V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub>	HIGH-level	A or B port; I <sub>O</sub> = -20 μA	[2]					
	output voltage	A port; V <sub>CC(A)</sub> = 1.4 V to 3.6 V		V <sub>CCO</sub> - 0.4	-	V <sub>CCO</sub> - 0.4	-	V
		B port; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		V <sub>CCO</sub> - 0.4	-	V <sub>CCO</sub> - 0.4	-	V
V <sub>OL</sub>	LOW-level	A or B port; I <sub>O</sub> = 20 μA	[2]					
	output voltage	A port; V <sub>CC(A)</sub> = 1.4 V to 3.6 V		-	0.4	-	0.4	V
		B port; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	0.4	-	0.4	V
lı	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	±2	-	±5	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μА
I <sub>OFF</sub>	power-off leakage	A port; $V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	±2	-	±10	μA
	current	B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±10	μΑ

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions	-40 °C t	:o +85 °C	-40 °C to	Unit	
			Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$ [1]					
		I <sub>CC(A)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μΑ
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μΑ
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	-	2	-	15	μΑ
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	-	-2	-	-15	μA
		I <sub>CC(B)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μΑ
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	13	-	65	μΑ
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	-	-2	-	-15	μΑ
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$					
		V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	15	-	70	μΑ

<sup>[1]</sup>  $V_{CCI}$  is the supply voltage associated with the input.

<sup>[2]</sup> V<sub>CCO</sub> is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 10. Dynamic characteristics

#### Table 9. Typical dynamic characteristics for temperature 25 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

Symbol	Parameter	Conditions	$V_{CC(B)}$					
			1.8 V	2.5 V	3.3 V	5.0 V		
V <sub>CC(A)</sub> =	1.2 V; T <sub>amb</sub> = 25 °C				-		-	
t <sub>pd</sub>	propagation delay	A to B	6.9	5.6	5.1	4.9	ns	
		B to A	7.1	5.8	5.0	5.1	ns	
t <sub>en</sub>	enable time	OE to A, B	500	500	500	500	ns	
t <sub>dis</sub>	disable time	OE to A; no external load [2]	14.5	14.5	14.5	14.5	ns	
		OE to B; no external load [2]	12.2	10.1	9.3	8.7	ns	
		OE to A; see Fig. 3	87	87	87	87	ns	
		OE to B; see Fig. 3	98	71	101	68	ns	
t <sub>t</sub>	transition time	A port	4.2	4.2	4.2	4.2	ns	
		B port	2.7	2.0	1.7	1.5	ns	
t <sub>sk(o)</sub>	output skew time	between channels [3]	1.4	0.7	0.6	0.5	ns	
t <sub>W</sub>	pulse width	data inputs	13	13	13	13	ns	
f <sub>data</sub>	data rate		60	60	60	60	Mbps	

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

Symbol	Parameter	Conditions			Unit						
			1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V										
t <sub>pd</sub>	propagation	A to B	1.4	11.4	1.2	8.0	1.1	6.7	8.0	6.2	ns
	delay	B to A	0.9	10.8	0.7	8.3	0.4	7.8	0.3	7.2	ns
t <sub>en</sub>	enable time	OE to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	3.7	18.0	3.7	18.0	3.7	18.0	3.7	18.0	ns
		OE to B; no external load [2]	3.7	19.5	3.5	15.0	3.0	13.0	1.7	11.5	ns
		OE to A; see Fig. 3	-	100	-	100	-	100	-	100	ns
		OE to B; see Fig. 3	-	150	-	105	-	150	-	105	ns
t <sub>t</sub>	transition	A port	0.8	6.5	0.8	6.3	0.8	6.3	0.8	6.3	ns
	time	B port	1.0	7.3	0.7	4.9	0.7	4.6	0.6	4.6	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	2.6	-	1.9	-	1.6	-	1.3	ns
t <sub>W</sub>	pulse width	data inputs	20	-	20	-	20	-	20	-	ns
f <sub>data</sub>	data rate		-	50	-	50	-	50	-	50	Mbps

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}$ .

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

<sup>[2]</sup> These values are guaranteed by design.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol Parameter	Parameter	Conditions	V <sub>CC(B)</sub>								Unit
			1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V										
t <sub>pd</sub>	propagation	A to B	1.6	10.8	1.4	7.9	1.3	6.2	1.2	5.3	ns
	delay	B to A	1.5	9.2	1.3	7.2	0.8	6.3	0.5	5.8	ns
t <sub>en</sub>	enable time	OE to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	2.9	13.0	2.9	13.0	2.9	13.0	2.9	13.0	ns
		OE to B; no external load [2]	4.0	18.0	3.0	13.0	2.5	11.5	1.5	9.5	ns
		OE to A; see Fig. 3	-	120	-	120	-	120	-	120	ns
		OE to B; see Fig. 3	-	150	-	105	-	150	-	105	ns
t <sub>t</sub>	transition	A port	0.7	5.1	0.7	5.0	1.0	5.0	0.7	5.0	ns
	time	B port	1.0	7.3	0.7	5.0	0.7	3.9	0.6	3.8	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	0.8	-	0.7	-	0.6	-	0.6	ns
t <sub>W</sub>	pulse width	data inputs	19	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate		-	52	-	60	-	60	-	60	Mbps
V <sub>CC(A)</sub> = :	2.5 V ± 0.2 V					•					
t <sub>pd</sub>	propagation	A to B	-	-	1.1	7.5	1.0	5.2	0.9	4.2	ns
	delay	B to A	-	-	1.0	5.6	0.6	5.0	0.3	4.2	ns
t <sub>en</sub>	enable time	OE to A, B	-	-	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	-	-	2.5	8.0	2.5	8.0	2.5	8.0	ns
		OE to B; no external load [2]	-	-	2.0	11.5	2.8	9.5	1.2	8.0	ns
		OE to A; see Fig. 3	-	-	-	85	-	85	-	85	ns
		OE to B; see Fig. 3	-	-	-	105	-	150	-	100	ns
t <sub>t</sub>	transition	A port	-	-	0.8	3.6	0.6	3.6	0.5	3.5	ns
	time	B port	-	-	0.6	4.9	0.7	3.9	0.6	3.2	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	0.4	-	0.3	-	0.3	ns
t <sub>W</sub>	pulse width	data inputs	-	-	13	-	10	-	10	-	ns
f <sub>data</sub>	data rate		-	-	-	80	-	100	-	100	Mbps

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol Parameter		Conditions	V <sub>CC(B)</sub>								
			1.8 V ±	0.15 V	2.5 V ±	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> = 3	3.3 V ± 0.3 V										
t <sub>pd</sub>	propagation	A to B	-	-	-	-	0.9	4.8	0.8	3.9	ns
	delay	B to A	-	-	-	-	0.5	4.3	0.2	3.7	ns
t <sub>en</sub>	enable time	OE to A, B	-	-	-	-	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	-	-	-	-	2.1	6.5	2.0	6.5	ns
		OE to B; no external load [2]	-	-	-	-	1.0	8.5	1.7	7.0	ns
		OE to A; see Fig. 3	-	-	-	-	-	125	-	125	ns
		OE to B; see Fig. 3	-	-	-	-	-	150	-	100	ns
t <sub>t</sub>	transition	A port	-	-	-	-	0.5	3.0	0.5	3.0	ns
	time	B port	-	-	-	-	0.7	3.9	0.6	3.2	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	-	-	0.4	-	0.3	ns
t <sub>W</sub>	pulse width	data inputs	-	-	-	-	9.0	-	9.0	-	ns
f <sub>data</sub>	data rate		-	-	-	-	-	110	-	110	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

#### Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

Symbol	Parameter	neter Conditions		V <sub>CC(B)</sub>								
			1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max		
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V		•		•							
t <sub>pd</sub>	propagation	A to B	1.4	11.9	1.2	9.0	1.1	7.3	0.8	6.5	ns	
	delay	B to A	0.9	10.9	0.7	8.8	0.4	7.9	0.3	7.7	ns	
t <sub>en</sub>	enable time	OE to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs	
t <sub>dis</sub>	disable time	OE to A; no external load [2]	3.7	19.0	3.7	19.0	3.7	19.0	3.7	19.0	ns	
		OE to B; no external load [2]	3.7	22.0	3.5	16.0	3.0	14.0	1.7	12.5	ns	
		OE to A; see Fig. 3	-	105	-	105	-	105	-	105	ns	
		OE to B; see Fig. 3	-	155	-	110	-	155	-	105	ns	
t <sub>t</sub>	transition	A port	0.8	8.1	0.8	7.9	0.8	7.9	0.8	7.9	ns	
	time	B port	1.0	9.1	0.7	6.1	0.7	5.8	0.6	5.8	ns	
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	2.6	-	1.9	-	1.6	-	1.3	ns	
t <sub>W</sub>	pulse width	data inputs	25	-	25	-	25	-	25	-	ns	
f <sub>data</sub>	data rate		-	40	-	40	-	40	-	40	Mbps	

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $<sup>\</sup>mathbf{t_{t}}$  is the same as  $\mathbf{t_{THL}}$  and  $\mathbf{t_{TLH}}$ 

<sup>[2]</sup> These values are guaranteed by design.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol Parameter	Conditions				Vcc	(B)				Unit	
			1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V										
t <sub>pd</sub>	propagation	A to B	1.6	11.1	1.4	8.1	1.3	6.5	1.2	5.5	ns
	delay	B to A	1.5	9.6	1.2	7.8	0.8	6.6	0.5	6.3	ns
t <sub>en</sub>	enable time	OE to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	2.9	14.0	2.9	14.0	2.9	14.0	2.9	14.0	ns
		OE to B; no external load [2]	4.0	20.5	3.0	14.5	2.5	12.5	1.5	10.5	ns
		OE to A; see Fig. 3	-	125	-	125	-	125	-	125	ns
		OE to B; see Fig. 3	-	150	-	105	-	150	-	105	ns
t <sub>t</sub>	transition	A port	0.8	6.4	0.7	6.3	1.0	6.3	0.7	6.3	ns
	time	B port	1.0	9.1	0.7	6.3	0.7	4.9	0.6	4.8	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	0.8	-	0.7	-	0.6	-	0.6	ns
t <sub>W</sub>	pulse width	data inputs	22	-	18	-	18	-	18	-	ns
f <sub>data</sub>	data rate		-	45	-	55	-	55	-	55	Mbps
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V										
t <sub>pd</sub>	propagation	A to B	-	-	1.1	7.6	1.0	5.8	0.9	4.4	ns
	delay	B to A	-	-	1.0	7.1	0.6	5.1	0.3	4.8	ns
t <sub>en</sub>	enable time	OE to A, B	-	-	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	-	-	2.5	9.0	2.5	9.0	2.5	9.0	ns
		OE to B; no external load [2]	-	-	2.0	13.0	2.8	10.5	1.2	8.5	ns
		OE to A; see Fig. 3	-	-	-	85	-	85	-	85	ns
		OE to B; see Fig. 3	-	-	-	105	-	150	-	100	ns
t <sub>t</sub>	transition	A port	-	-	0.8	4.5	0.6	4.5	0.5	4.4	ns
	time	B port	-	-	0.6	6.1	0.7	4.9	0.6	4.0	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	0.4	-	0.3	-	0.3	ns
t <sub>W</sub>	pulse width	data inputs	-	-	13	-	13	-	13	-	ns
f <sub>data</sub>	data rate		-	-	-	75	-	80	-	80	Mbps

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol Parameter		Conditions	V <sub>CC(B)</sub>								
			1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} = 3$	3.3 V ± 0.3 V										
t <sub>pd</sub>	propagation	A to B	-	-	-	-	0.9	5.3	0.8	4.2	ns
l	delay	B to A	-	-	-	-	0.5	4.4	0.2	4.0	ns
t <sub>en</sub>	enable time	OE to A, B	-	-	-	-	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load [2]	-	-	-	-	2.1	7.0	2.0	7.0	ns
l		OE to B; no external load [2]	-	-	-	-	1.0	9.5	1.7	7.5	ns
l		OE to A; see Fig. 3	-	-	-	-	-	125	-	125	ns
l		OE to B; see Fig. 3	-	-	-	-	-	150	-	100	ns
t <sub>t</sub>	transition	A port	-	-	-	-	0.5	3.8	0.5	3.8	ns
l	time	B port	-	-	-	-	0.7	4.9	0.6	4.0	ns
t <sub>sk(o)</sub>	output skew time	between channels [3]	-	-	-	-	-	0.4	-	0.3	ns
t <sub>W</sub>	pulse width	data inputs	-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate		-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

#### Table 12. Typical power dissipation capacitance [1][2]

Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions				Vc	C(A)			Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
						Vc	C(B)	•		
			1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
T <sub>amb</sub> = 2	5 °C									
C <sub>PD</sub>	power	outputs enabled; OE = V <sub>CC(A)</sub>								
	dissipation capacitance	A port: (direction A to B)	7.0	6.5	7.2	7.6	7.6	7.0	8.0	pF
	Capacitarioc	A port: (direction B to A)	9.6	10.0	9.8	10.1	10.5	10.3	10.8	pF
		B port: (direction A to B)	23.3	28.7	23.1	23.1	23.7	25.9	25.9	pF
		B port: (direction B to A)	17.8	25.5	17.1	16.8	17.4	21.0	20.5	pF
		outputs disabled; OE = GND								
		A port: (direction A to B)	0.2	0.2	0.2	0.3	0.3	0.3	0.3	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.02	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.2	0.3	0.2	0.2	0.3	0.3	0.3	pF

<sup>[1]</sup>  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu$ W).  $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:  $f_i$  = input frequency in MHz;  $f_o$  = output frequency in MHz;

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}$ .

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $<sup>\</sup>mathbf{t_{t}}$  is the same as  $\mathbf{t_{THL}}$  and  $\mathbf{t_{TLH}}$ 

These values are guaranteed by design.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

 $C_L$  = load capacitance in pF;  $V_{CC}$  = supply voltage in V;

N = number of inputs switching;  $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs. [2]  $f_i = 10$  MHz;  $V_i = GND$  to  $V_{CC}$ ;  $t_r = t_f = 1$  ns;  $C_L = 0$  pF;  $R_L = \infty \Omega$ .

#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 10.1. Waveforms and test circuit

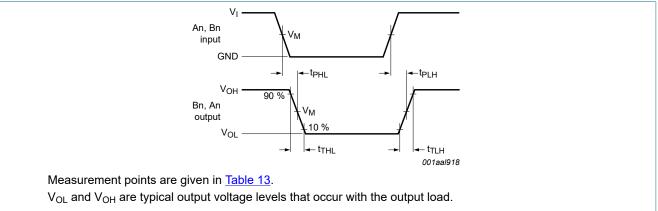


Fig. 2. The data input (An, Bn) to data output (Bn, An) propagation delay times

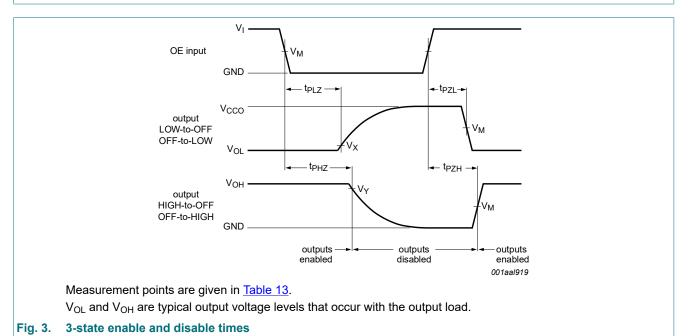
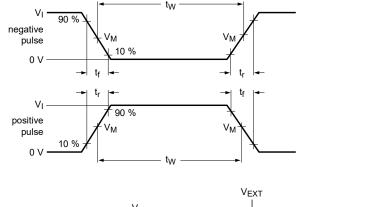


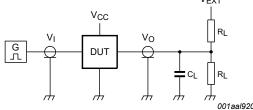
Table 13. Measurement points [1]

Table 10. Measureme	int bounto [1]			
Supply voltage	Input	Output		
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> - 0.1 V
1.5 V ± 0.1 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> - 0.1 V
1.8 V ± 0.15 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V
2.5 V ± 0.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V
3.3 V ± 0.3 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V
5.0 V ± 0.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V

<sup>[1]</sup>  $V_{CCI}$  is the supply voltage associated with the input and  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state





Test data is given in Table 14.

All input pulses are supplied by generators having the following characteristics:

PRR  $\leq$  10 MHz;  $Z_O = 50 \Omega$ ;  $dV/dt \geq 1.0 V/ns$ .

Definitions test circuit:

R<sub>L</sub> = Load resistance;

 $C_L$  = Load capacitance including jig and probe capacitance;

V<sub>EXT</sub> = External voltage for measuring switching times.

Fig. 4. Test circuit for measuring switching times

Table 14. Test data

Supply voltag	je	Input		Load		V <sub>EXT</sub>			
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>I</sub> [1]	Δt/ΔV	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]	
1.2 V to 3.6 V	1.65 V to 5.5 V	$V_{CCI}$	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>	

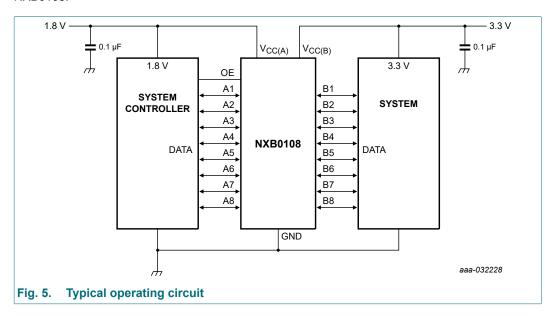
- [1] V<sub>CCI</sub> is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 \text{ M}\Omega$ ; for measuring enable and disable times,  $R_L = 50 \text{ k}\Omega$ .
- [3] V<sub>CCO</sub> is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 11. Application information

#### 11.1. Applications

Voltage level-translation applications. The NXB0108 can be used to interface between devices or systems operating at different supply voltages. See <u>Fig. 5</u> for a typical operating circuit using the NXB0108.

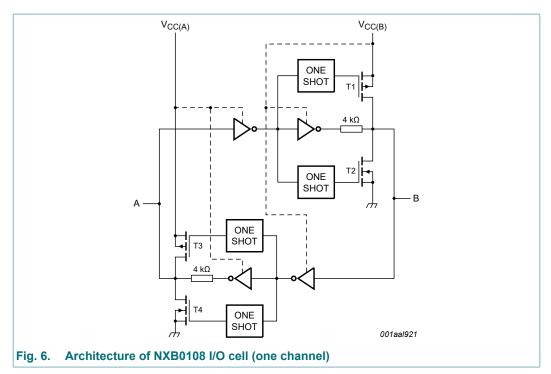


#### 11.2. Architecture

The architecture of the NXB0108 is shown in Fig. 6. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NXB0108 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70  $\Omega$  at  $V_{\rm CCO}$  = 1.2 V to 1.8 V, 50  $\Omega$  at  $V_{\rm CCO}$  = 1.8 V to 3.3 V and 40  $\Omega$  at  $V_{\rm CCO}$  = 3.3 V to 5.0 V.

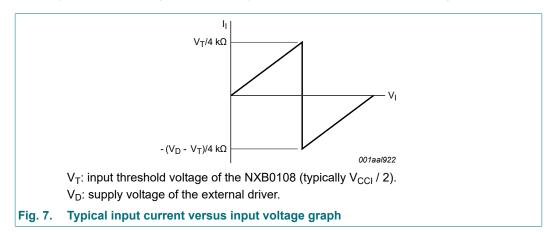
NXB0108PWJ Nexperia USA Inc. IC TRANSLATOR BIDIR 20TSSOP

#### Dual supply translating transceiver; auto direction sensing; 3-state



#### 11.3. Input driver requirements

For correct operation, the device driving the data I/Os of the NXB0108 must have a minimum drive capability of ±2 mA. See Fig. 7 for a plot of typical input current versus input voltage.



#### 11.4. Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NXB0108 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 11.5. Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

#### 11.6. Pull-up or pull-down resistors on I/O lines

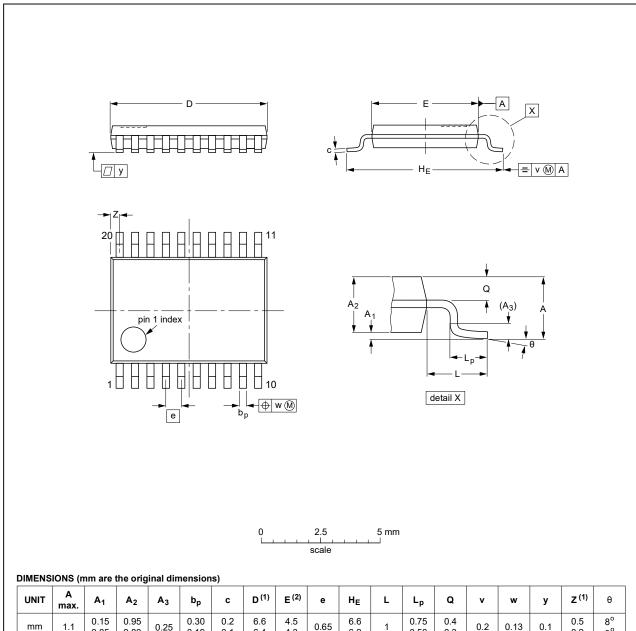
As mentioned previously the NXB0108 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k $\Omega$ . For this reason the NXB0108 is not recommended for use in open drain driver applications such as 1-Wire or I $^2$ C. For these applications, the NXS0108 level translator is recommended.

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 12. Package outline

#### TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm

SOT360-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	6.6 6.4	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.5 0.2	8° 0°

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT360-1		MO-153			<del>99-12-27</del> 03-02-19

Fig. 8. Package outline SOT360-1 (TSSOP20)

#### Dual supply translating transceiver; auto direction sensing; 3-state

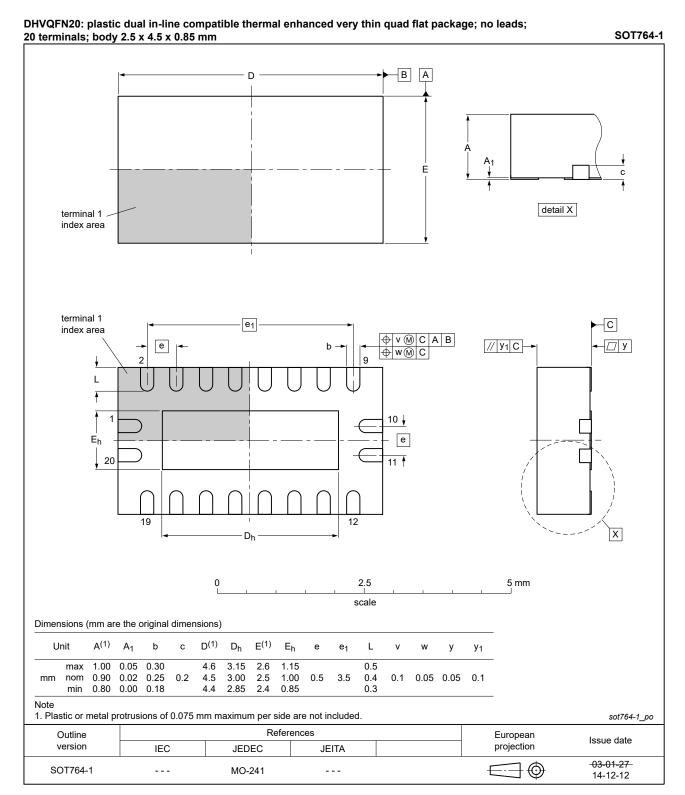


Fig. 9. Package outline SOT764-1 (DHVQFN20)

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 13. Abbreviations

#### **Table 15. Abbreviations**

Acronym	Description
ANSI	American National Standards Institute
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	Electro Static Discharge
ESDA	ElectroStatic Discharge Association
НВМ	Human Body Model
JEDEC	Joint Electron Device Engineering Council

## 14. Revision history

#### **Table 16. Revision history**

Document ID	Release date	Data sheet status	Change notice	Supersedes
NXB0108 v.2.1	20240731	Product data sheet	-	NXB0108 v.2
NXB0108 v.2	20211103	Product data sheet	-	NXB0108 v.1
Modifications:	• Fig. 1 updated			
NXB0108 v.1	20200903	Product data sheet	-	-

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 15. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <a href="https://www.nexperia.com">https://www.nexperia.com</a>.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

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