

# **RT7306DGS Datasheet**



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DiGi Electronics Part Number RT7306DGS-DG

Manufacturer Richtek USA Inc.

Manufacturer Product Number RT7306DGS

Description IC LED DRIVER OFFL ANALOG 8SOP

Detailed Description LED Driver IC 1 Output AC DC Offline Switcher Flyback, Step-Down (Buck), Step-Up (Boost) Analog Dim

ming 8-SOP



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## **Purchase and inquiry**

Manufacturer Product Number:	Manufacturer:
RT7306DGS	Richtek USA Inc.
Series:	Product Status:
	Active
Type:	Topology:
AC DC Offline Switcher	Flyback, Step-Down (Buck), Step-Up (Boost)
Internal Switch(s):	Number of Outputs:
No	1
Voltage - Supply (Min):	Voltage - Supply (Max):
11V	34V
Voltage - Output:	Current - Output / Channel:
Frequency:	Dimming:
	Analog
Applications:	Operating Temperature:
Lighting	-40°C ~ 125°C (TJ)
Mounting Type:	Package / Case:
Surface Mount	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package:	Base Product Number:
8-SOP	RT7306

## **Environmental & Export classification**

8542.39.0001

RoHS Status:	Moisture Sensitivity Level (MSL):
ROHS3 Compliant	3 (168 Hours)
REACH Status:	ECCN:
REACH Unaffected	EAR99
HTSUS:	



# Primary-Side Regulation Dimmable LED Driver Controller with Active-PFC

## **General Description**

The RT7306D is a constant current LED driver with active power factor correction. It supports high power factor across a wide range of line voltages, and it drives the converter in the Quasi-Resonant (QR) mode to achieve higher efficiency. By using Primary Side Regulation (PSR), the RT7306D controls the output current accurately without a shunt regulator and an opto-coupler at the secondary side, reducing the external component count, the cost, and the volume of the driver board.

The RT7306D is compatible with analog dimming. The output current can be modulated by the DIM pin. An in-house design high voltage (HV) start-up device is integrated in the RT7306D to minimize the power loss and shorten the start-up time.

The RT7306D embeds comprehensive protection functions for robust designs, including LED open-circuit protection, LED short-circuit protection, output diode short-circuit protection, VDD Under-Voltage Lockout (UVLO), VDD Over-Voltage Protection (VDD OVP), Over-Temperature Protection (OTP), and cycle-by-cycle current limitation.

#### **Features**

- Tight LED Current Regulation
- No Opto-Coupler and TL431 Required
- Power Factor Correction (PFC)
- Compatible with Analog Dimming
- Built-In HV Start-Up Device
- Quasi-Resonant
- Maximum/Minimum Switching Frequency Clamping
- Maximum/Minimum On-Time Limitation
- Wide VDD Range (up to 34V)
- THD Optimization
- Input-Voltage Feed-Forward Compensation
- Multiple Protection Features
  - **▶ LED Open-Circuit Protection**
  - **▶ LED Short-Circuit Protection**
  - **▶** Output Diode Short-Circuit Protection
  - ▶ VDD Under-Voltage Lockout
  - **▶ VDD Over-Voltage Protection**
  - **▶** Over-Temperature Protection
  - ▶ Cycle-by-Cycle Current Limitation

## **Applications**

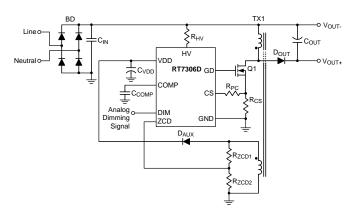
• AC-DC LED Lighting Driver

## **Simplified Application Circuit**

#### **Flyback Application Circuit**

# Neutral O Line O CIN RT7306D RT7306D COMP COMP

## **Buck-Boost Application Circuit**





## **Ordering Information**

RT7306D Package Type
S: SOP-8

Lead Plating System
G: Green (Halogen Free and Pb Free)

#### Note:

## Richtek products are:

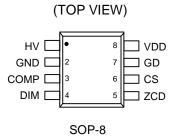
- ▶ RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

## **Marking Information**

RT7306D GSYMDNN

RT7306DGS : Product Number YMDNN : Date Code

## **Pin Configuration**

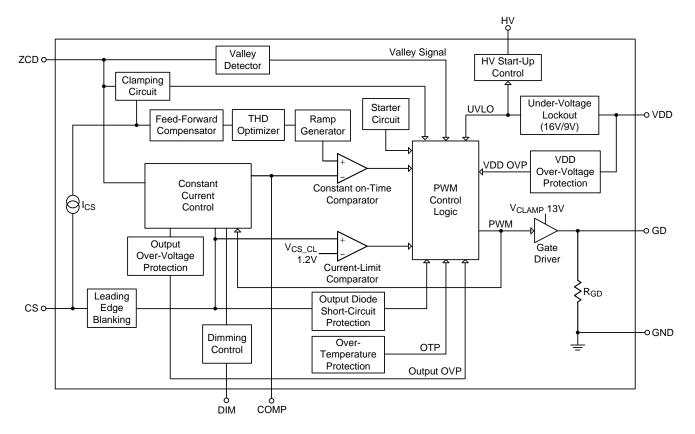


## **Functional Pin Description**

Pin No.	Pin Name	Pin Function
1	HV	High voltage input for startup.
2	GND	Ground of the controller.
3	COMP	Compensation node. Output of the internal trans-conductance amplifier.
4	DIM	Analog dimming signal input. LED driving current can be adjusted by an analog voltage.
5	ZCD	Zero current detection input. This pin is used to sense the voltage at auxiliary winding of the transformer.
6	CS	Current sense input. Connect this pin to the current sense resistor.
7	GD	Gate driver output for external power MOSFET.
8	VDD	Supply voltage ( $V_{DD}$ ) input. The controller will be enabled when $V_{DD}$ exceeds $V_{TH\_ON}$ and disabled when $V_{DD}$ is lower than $V_{TH\_OFF}$ .



## **Functional Block Diagram**



## **Operation**

# Critical-Conduction Mode (CRM) with Constant On-Time Control

Figure 1 shows a typical flyback converter with input voltage ( $V_{IN}$ ). When main switch Q1 is turned on with a fixed on-time ( $t_{ON}$ ), the peak current ( $I_{L\_PK}$ ) of the magnetic inductor ( $L_m$ ) can be calculated by the following equation :

$$I_{L\_PK} = \frac{V_{IN}}{L_m} \times t_{ON}$$

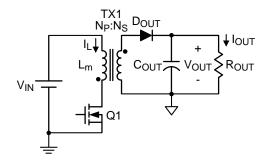


Figure 1. Typical Flyback Converter

If the input voltage is the output voltage of the full-bridge rectifier with sinusoidal input voltage  $(V_{IN\_PK\cdot sin(\theta)})$ , the inductor peak current  $(I_{L\_PK})$  can be expressed as the following equation :

$$I_{L\_PK} = \frac{V_{IN\_PK} \times \left| sin(\theta) \right| \times t_{ON}}{L_m}$$

When the converter operates in CRM with constant on-time control, the envelope of the peak inductor current will follow the input voltage waveform with in-phase. Thus, high power factor can be achieved, as shown in Figure 2.



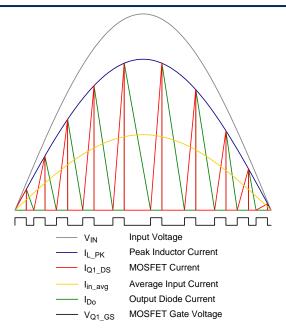


Figure 2. Inductor Current of CRM with Constant
On-Time Control

The RT7306D needs no shunt regulator and opto-coupler at the secondary side to achieve the output current regulation. Figure 3 shows several key waveforms of a conventional flyback converter in Quasi-Resonant (QR) mode, in which VAUX is the voltage on the auxiliary winding of the transformer.

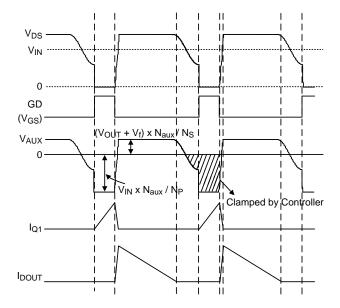


Figure 3. Key Waveforms of a Flyback Converter

## **Voltage Clamping Circuit**

The RT7306D provides a voltage clamping circuit at ZCD pin since the voltage on the auxiliary winding is negative when the main switch is turned on. The lowest voltage on ZCD pin is clamped near zero to prevent the IC from being damaged by the negative voltage. Meanwhile, the sourcing ZCD current (IzcD\_SH), flowing through the upper resistor (RZCD1), is sampled and held to be a line-voltage-related signal for propagation delay compensation. The RT7306D embeds programmable the propagation delay compensation through CS pin. A sourcing current ICS (equal to Izcd sh x Kpc) applies a voltage offset (Ics x RPC) which is proportional to line voltage on CS to compensate the propagation delay effect. Thus, the output current can be equal at high and low line voltage.

#### **Quasi-Resonant Operation**

Figure 4 illustrates how valley signal triggers PWM. If no valley signal detected for a long time, the next PWM is triggered by a starter circuit at end of the interval ( $t_{START}$ , 130 $\mu$ s typ.) which starts at the rising edge of the previous PWM signal. A blanking time ( $t_{S(MIN)}$ , 8.5 $\mu$ s typ.), which starts at the rising edge of the previous PWM signal, limits minimum switching period. When the  $t_{S(MIN)}$  interval is on-going, all of valley signals are not allowed to trigger the next PWM signal. After the end of the  $t_{S(MIN)}$  interval, the coming valley will trigger the next PWM signal. If one or more valley signals are detected during the  $t_{S(MIN)}$  interval and no valley is detected after the end of the  $t_{S(MIN)}$  interval, the next PWM signal will be triggered automatically at end of the  $t_{S(MIN)}$  + 5 $\mu$ s (typ.).

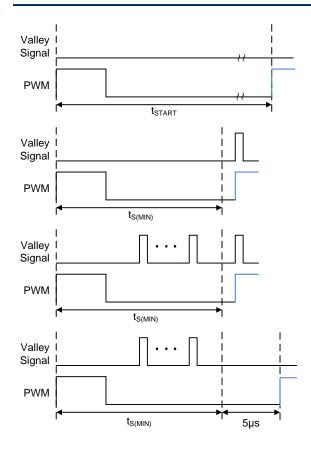


Figure 4. PWM Triggered Method

## **HV Start-Up Device**

An in-house design 500V start-up device is integrated in the RT7306D to minimize the power loss and shorten the start-up time. The HV start-up device will be turned on during start-up period and be turned off during normal operation. It provides fast start-up time and no power loss in this path during normal operation. A  $10k\Omega$  resistor is recommended to be connected in series with HV pin.

#### **Dimming Function**

An analog dimming function is embedded in the RT7306D. When the voltage on the DIM pin ( $V_{DIM}$ ) is within  $V_{DIM\_LOW}$  and  $V_{DIM\_HIGH}$ , the regulation factor of constant current control ( $K_{CC}$ ) is linearly proportional to  $V_{DIM}$ , as shown in Figure 5.

DIM pin sourcing a current ( $1\mu$ A typ.) when VDD > V<sub>TH\_ON</sub>, and the sourcing current is shut down after 100ms (typ.)

The external equivalent resistance of DIM pin is recommended to be higher than  $430k\Omega$ .

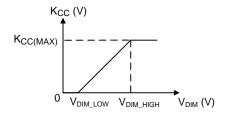


Figure 5. Dimming Curve

#### **Protections**

#### **LED Open-Circuit Protection**

In an event of output open circuit, the converter will be shut down to prevent being damaged, and it will be auto-restarted when the output is recovered. Once the LED is open-circuit, the output voltage keeps rising, causing the voltage on ZCD pin VzcD rising accordingly. When the sample-and-hold ZCD voltage (VzcD\_SH) exceeds its OV threshold (VzcD\_OVP, 3.2V typ.), output OVP will be activated and the PWM output (GD pin) will be forced low to turn off the main switch. If the output is still open-circuit when the converter restarts, the converter will be shut down again.

#### **Output Diode Short-Circuit Protection**

When the output diode is damaged as short-circuit, the transformer will be led to magnetic saturation and the main switch will suffer from a high current stress. To avoid the above situation, an output diode short-circuit protection is built-in. When CS voltage V<sub>CS</sub> exceeds the threshold (V<sub>CS\_SD</sub> 1.7 typ.) of the output diode short-circuit protection, the RT7306D will shut down the PWM output (GD pin) in few cycles to prevent the converter from damage. It will be auto-restarted when the failure condition is recovered.

# VDD Under-Voltage Lockout (UVLO) and Over-Voltage Protection (VDD OVP)

The RT7306D will be enabled when VDD voltage ( $V_{DD}$ ) exceeds rising UVLO threshold ( $V_{TH\_ON}$ , 17V typ.) and disabled when  $V_{DD}$  is lower than falling UVLO threshold ( $V_{TH\_OFF}$ , 8.5V typ.).

When  $V_{DD}$  exceeds its over-voltage threshold ( $V_{OVP}$ , 37.4V typ.), the PWM output of the RT7306D is shut down. It will be auto-restarted when the VDD is recovered to a normal level.



## **Over-Temperature Protection (OTP)**

The RT7306D provides an internal OTP function to protect the controller itself from suffering thermal stress and permanent damage. It's not suggested to use the function as precise control of over temperature. Once the junction temperature is higher than the OTP threshold ( $T_{SD}$ ,  $150^{\circ}$ C typ.), the controller will shut down until the temperature cools down by  $30^{\circ}$ C (typ.). Meanwhile, if  $V_{DD}$  reaches falling UVLO threshold voltage ( $V_{TH\_OFF}$ ), the controller will hiccup till the over temperature condition is removed.



## Absolute Maximum Ratings (Note 1)

7 110 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
• HV Pin	-0.3V to 500V
• Supply Voltage, V <sub>DD</sub>	-0.3V to 40V
Gate Driver Output, GD	-0.3V to 20V
• Other Pins	-0.3V to 6V
<ul> <li>Power Dissipation, P<sub>D</sub> @ T<sub>A</sub> = 25°C</li> </ul>	
SOP-8	- 0.48W
Package Thermal Resistance (Note 2)	
SOP-8, θJA	- 206.9°C/W
Lead Temperature (Soldering, 10 sec.)	- 260°C
Junction Temperature	- 150°C
Storage Temperature Range	- −65°C to 150°C
• ESD Susceptibility (Note 3)	
HBM (Human Body Model) (Except HV pin)	- 2kV
Recommended Operating Conditions (Note 4)	
Supply Input Voltage, V <sub>DD</sub>	11V to 34V

## **Electrical Characteristics**

(V<sub>DD</sub> = 15V, T<sub>A</sub> = 25°C, unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
HV Section						
HV Start-Up Average Current	I <sub>HV_ST</sub>	$V_{DD} < V_{TH\_ON}, V_{HV} = 100V$	1			mA
Off State Leakage Current		V <sub>DD</sub> = V <sub>TH_ON</sub> + 1V, V <sub>HV</sub> = 500V			30	μА
VDD Section						
VDD OVP Threshold Voltage	Vovp	V <sub>DD</sub> rising	35.4	37.4	39.4	V
Rising UVLO Threshold Voltage	VTH_ON		16	17	18	V
Falling UVLO Threshold Voltage	V <sub>TH_OFF</sub>		7.5	8.5	9.5	<b>V</b>
Fault Released Voltage	V <sub>TH_FR</sub>			6		V
VDD Holdup Mode Entry Point	V <sub>DD_ET</sub>			10		V
VDD Holdup Mode Ending Point	V <sub>DD_ED</sub>		1	10.5	1	<b>V</b>
Operating Current	I <sub>DD_OP</sub>	V <sub>DD</sub> = 15V, I <sub>ZCD</sub> = 0, GD open		2	3	mA
Operating Current at Shutdown		V <sub>DD</sub> = V <sub>TH_OFF</sub>		60		μΑ
Start-Up Current	I <sub>VDD_ST</sub>	V <sub>DD</sub> = V <sub>TH</sub> ON - 1V		15	30	μΑ
ZCD Section						
Lower Clamp Voltage	Vzcdl	I <sub>ZCD</sub> = 0 to -2.5mA	-50	0	60	mV
ZCD OVP Threshold Voltage	V <sub>ZCD_OVP</sub>		3.04	3.2	3.36	V



Sease Dimming Low Threshold voltage   VDIM_LOW   Sease Diver Section   VCS_CL   Sease Current Limitation at Joperation Delay Compensation Factor Section   VCS_CL   Sease Current Shutdown Voltage Current Shutdown Voltage   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS = KPC x   IZCD,   IZCD = 1.50 μA   VCS_CL   ICS_CL   ICS	Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Voltage	Dimming Control Section			1			
Voltage   Vol	Analog Dimming Low Threshold Voltage	V <sub>DIM_LOW</sub>		250	300	350	mV
Constant Current Control Section   Constant Current Control   Constant Control   Constant Current Control   Constant Current Control   Constant Current Control   Constant Current Control   Constant Control	Analog Dimming High Threshold Voltage	V <sub>DIM</sub> _HIGH			2.8		V
Alaximum Regulated Factor for constant-Current Control   KCC(MAX)   VDIM = 3V   246.25   250   253.75   mV     Alaximum Comp Voltage   VCOMP(MAX)   4.8   5.5     V     Alaximum Comp Voltage   VCOMP(MIN)     0.5     V     Alaximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Current Sense Section     LEB   240   400   570   ns     Leak Current Shutdown Voltage   VCS_SD   1.53   1.7   1.87   V     Leak Current Limitation at lormal Operation   VCS_CL   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     0.042     A/A     Compagation Delay Compensation Factor   Ics = KPC x IzCD, IzCD =     Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics = KPC x IzCD, IzCD =   Ics	DIM Sourcing Current			0.5	1	2	μΑ
Constant-Current Control   CCC(MAX)   VDIM = 3V   240.25   250   253.75   mV	<b>Constant Current Control Section</b>	on					
Maximum Comp Voltage   VCOMP(MIN)     0.5     V     Maximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Maximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Maximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Maximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Maximum Sourcing Current   IcoMP(MAX)   During start-up period     100     μA     Maximum Sourcing Edection   VCs_SD	Maximum Regulated Factor for Constant-Current Control	KCC(MAX)	V <sub>DIM</sub> = 3V	246.25	250	253.75	mV
Maximum Sourcing Current         IcomP(MAX)         During start-up period          100          μA           Autrent Sense Section         Eading Edge Blanking Time         tLEB         240         400         570         ns           Peak Current Shutdown Voltage Preshold         VCS_SD         1.53         1.7         1.87         V           Peak Current Limitation at Identical Operation         VCS_CL         Ics = KPC x IzCD, IZCD = 1.08         1.2         1.32         V           Propagation Delay Compensation Factor         KPC         Ics = KPC x IzCD, IZCD = 1.00.042          A/A           State Driver Section         Its No. In Impure Its No. In Impuration Its No. Its No. In Impure Its No. Its	Maximum Comp Voltage	VCOMP(MAX)		4.8	5.5		V
Part   Sense Section   Seak Current Shutdown Voltage   Vcs_SD   Vcs_SD   Seak Current Shutdown Voltage   Vcs_SD   Seak Current Limitation at Part   Sense Section   Seate Output Clamping Voltage   Vcs_CL   Seate Output Clamping Voltage   Vcl_AMP   VdD = 15V, CL = 1nF   Seate Output Clamping Voltage   VdD = 15V, CL = 1nF   Seate Output Clamping Voltage   VdD = 15V, CL = 1nF   Seate Output Clamping Voltage   VdD = 15V, CL = 1nF   Se	Minimum Comp Voltage	VCOMP(MIN)			0.5		V
Leading Edge Blanking Time   Leb   240   400   570   ns     Peak Current Shutdown Voltage   VCS_SD   1.53   1.7   1.87   V     Peak Current Limitation at   VCS_CL   1.08   1.2   1.32   V     Propagation Delay   Compensation Factor   VCS_CL   ICS = KPC x IZCD, IZCD =	Maximum Sourcing Current	ICOMP(MAX)	During start-up period		100		μΑ
Peak Current Shutdown Voltage   VCS_SD	<b>Current Sense Section</b>						
1.53   1.7   1.87   V   1.87   V   2   2   2   2   2   2   2   2   2	Leading Edge Blanking Time	tLEB		240	400	570	ns
lormal Operation $V_{CS\_CL}$	Peak Current Shutdown Voltage Threshold	V <sub>CS_SD</sub>		1.53	1.7	1.87	V
Compensation Factor $RPC$ $-150\mu A$	Peak Current Limitation at Normal Operation	Vcs_cl		1.08	1.2	1.32	V
tising Time $t_R$ $V_{DD} = 15V$ , $C_L = 1nF$ $$ $140$ $250$ $ns$ falling Time $t_F$ $V_{DD} = 15V$ , $C_L = 1nF$ $$ $40$ $70$ $ns$ $t_{CAMP}$ $t_{CAM$	Propagation Delay Compensation Factor	K <sub>PC</sub>	•		0.042		A/A
Falling Time to $V_{DD} = 15V$ , $C_L = 1nF$ and $V_{DD} = 15V$ , $C_L = 1nF$ and $V_{DD} = 15V$ , $V_{DD} = 15V$	Gate Driver Section						
Sate Output Clamping Voltage $V_{CLAMP}$ $V_{DD} = 15V, C_L = 1nF$ $10.8$ $12$ $13.2$ $V_{CLAMP}$ Internal Pull Low Resistor $V_{CLAMP}$ $V_{DD} = 15V, C_L = 1nF$ $V_{CLAMP}$	Rising Time	t <sub>R</sub>	V <sub>DD</sub> = 15V, C <sub>L</sub> = 1nF		140	250	ns
Timing Control Section  Minimum On-Time $t_{ON(MIN)}$ $t_{IZCD} = -150\mu A$ $t_{IZCD} = -150\mu$	Falling Time	tF	V <sub>DD</sub> = 15V, C <sub>L</sub> = 1nF		40	70	ns
Timing Control Section       Minimum On-Time $t_{ON(MIN)}$ $I_{ZCD} = -150\mu A$ 0.9     1.25     1.6     μs       Minimum Switching Period $t_{S(MIN)}$ 7     8.5     10     μs       Duration of Starter at Normal Operation $t_{START}$ 75     130     300     μs	Gate Output Clamping Voltage	VCLAMP	$V_{DD} = 15V, C_L = 1nF$	10.8	12	13.2	V
Minimum On-Time $t_{ON(MIN)}$ $I_{ZCD} = -150\mu A$ 0.91.251.6μsMinimum Switching Period $t_{S(MIN)}$ 78.510μsDuration of Starter at Normal Operation $t_{START}$ 75130300μs	Internal Pull Low Resistor	R <sub>GD</sub>			40		$k\Omega$
Minimum Switching Period t <sub>S(MIN)</sub> 7 8.5 10 μs Ouration of Starter at Normal t <sub>START</sub> 75 130 300 μs	<b>Timing Control Section</b>						
Duration of Starter at Normal Operation 75 130 300 μs	Minimum On-Time	ton(MIN)	I <sub>ZCD</sub> = -150μA	0.9	1.25	1.6	μS
Deperation tstart /5 130 300 μs	Minimum Switching Period	ts(MIN)		7	8.5	10	μS
	Duration of Starter at Normal Operation	tstart		75	130	300	μS
Maximum On-Time toN(MAX) 29 47 65 μs	Maximum On-Time	ton(MAX)		29	47	65	μS
Over-Temperature Protection (OTP) Section							
OTP Temperature Threshold Totp (Note 5) 150 °C	OTP Temperature Threshold	Тотр	(Note 5)		150		°C
OTP Temperature Hysteresis Totp-Hys (Note 5) 30 °C	OTP Temperature Hysteresis	T <sub>OTP-HYS</sub>	(Note 5)		30		°C

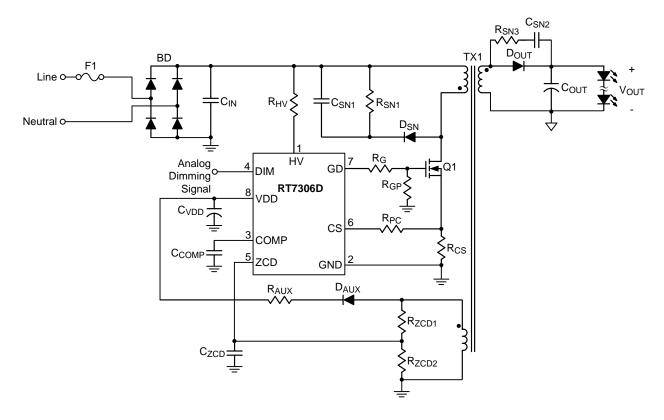
- **Note 1.** Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
- Note 2.  $\theta_{JA}$  is measured under natural convection (still air) at  $T_A = 25^{\circ}\text{C}$  with the component mounted on a low effective-thermal-conductivity two-layer test board on a JEDEC thermal measurement standard.
- Note 3. Devices are ESD sensitive. Handling precaution recommended.
- **Note 4.** The device is not guaranteed to function outside its operating conditions.
- Note 5. Guarantee by design.



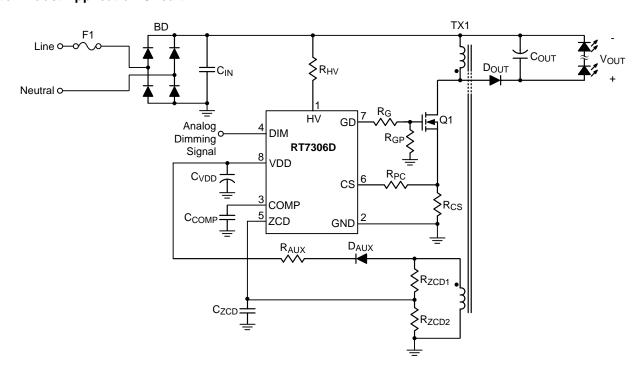
## **RICHTEK**

## **Typical Application Circuit**

## **Flyback Application Circuit**

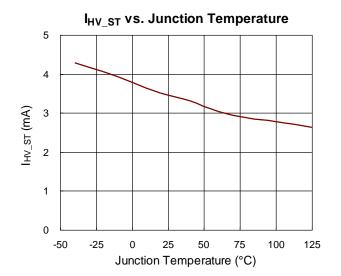


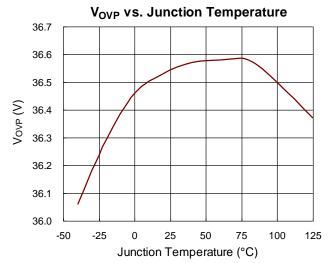
## **Buck-Boost Application Circuit**

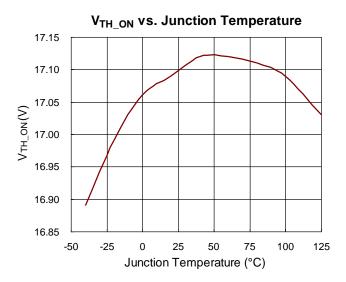


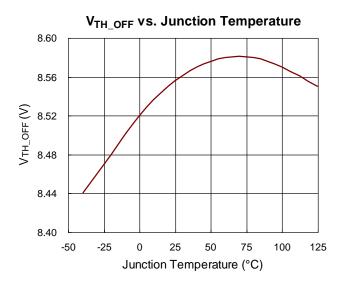


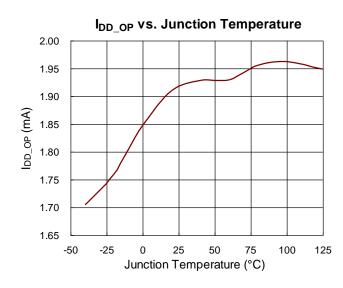
## **Typical Operating Characteristics**

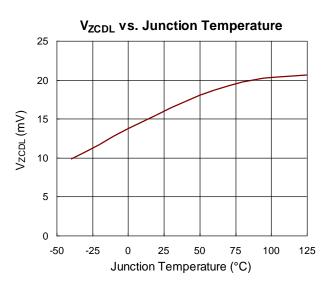




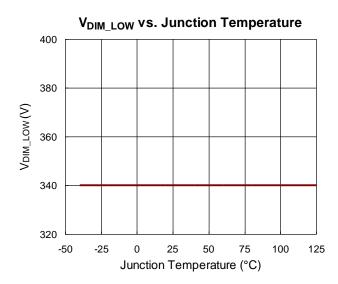


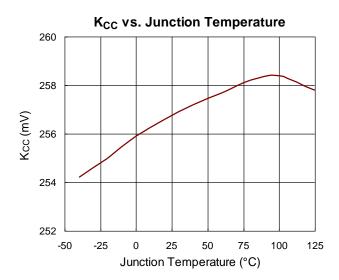


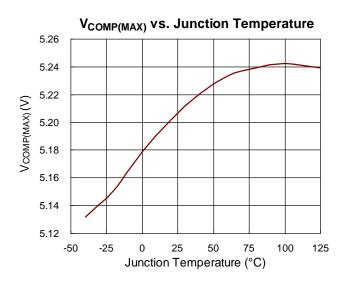


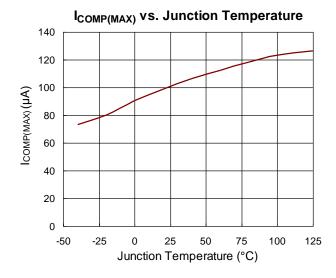


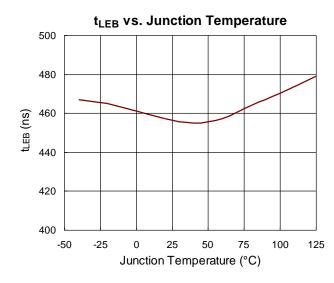
## **RICHTEK**

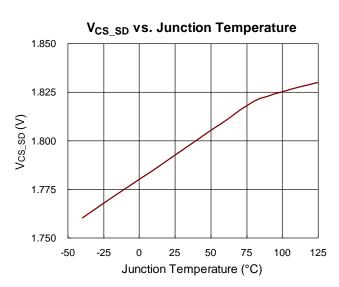




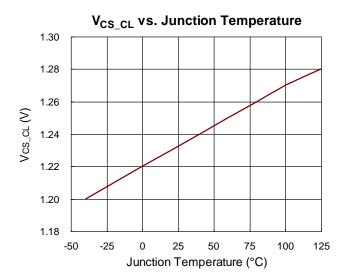


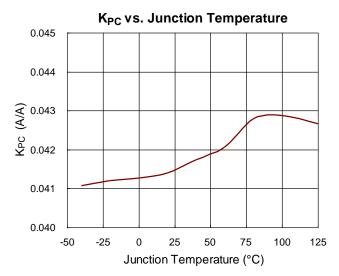


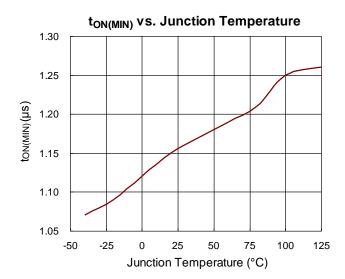


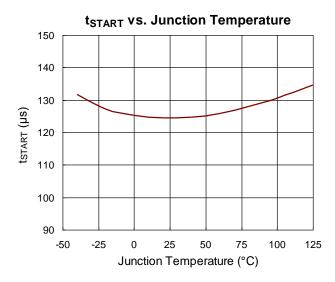


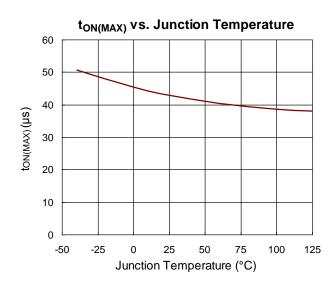












## **Application Information**

#### **Output Current Setting**

Considering the conversion efficiency, the programmed DC level of the average output current ( $I_{OUT}(t)$ ) can be derived as :

$$I_{OUT\_CC} = \frac{1}{2} \times \frac{NP}{NS} \times \frac{KCC}{RCS} \times CTR_{TX1}$$

$$CTR_{TX1} = \frac{I_{SEC\_PK}}{I_{PRI\_PK}} \times \frac{N_S}{N_P}$$

in which CTR<sub>TX1</sub> is the current transfer ratio of the transformer TX1,  $I_{SEC\_PK}$  is the peak current of the secondary side, and  $I_{PRI\_PK}$  is the peak current of the primary side. CTR<sub>TX1</sub> can be estimated to be 0.9. According to the above parameters, current sense resistor  $R_{CS}$  can be determined as the following equation:

$$RCS = \frac{1}{2} \times \frac{NP}{NS} \times \frac{KCC}{I_{OUT} CC} \times CTR_{TX1}$$

#### **Propagation Delay Compensation Design**

The  $V_{CS}$  deviation ( $\Delta V_{CS}$ ) caused by propagation delay effect can be derived as:

$$\Delta V_{CS} = \frac{V_{IN} \cdot t_D \cdot R_{CS}}{L_m} \; , \label{eq:deltaVCS}$$

in which  $t_{\rm D}$  is the delay period which includes the propagation delay of the RT7306D and the turn-off transition of the main MOSFET. The sourcing current from CS pin of the RT7306D (Ics) can be expressed as:

$$I_{CS} = K_{PC} \cdot V_{IN} \cdot \frac{N_A}{N_P} \cdot \frac{1}{R_{ZCD1}}$$

where  $N_A$  is the turns number of the auxiliary winding.  $R_{PC}$  can be designed by :

$$R_{PC} = \frac{\Delta V_{CS}}{I_{CS}} = \frac{t_D \cdot R_{CS} \cdot R_{ZCD1}}{L_m \cdot K_{PC}} \cdot \frac{N_P}{N_A}$$

## **Feed-Forward Compensation Design**

The COMP voltage,  $V_{COMP}$ , is a function of the resistor  $R_{ZCD1}$  as following :

$$R_{ZCD1} = \left(V_{IN\_pk} \times \frac{N_A}{N_P} \times K_{IV}\right) \times \sqrt{\frac{\left(\frac{t_{ON}}{t_S}\right) \times Gm_{ramp} \times t_{ON}}{2 \times C_{ramp} \times \left(V_{COMP} - V_D\right)}}$$

in which  $K_{IV}$ ,  $Gm_{ramp}$ , and  $C_{ramp}$  are fixed parameters in the RT7306D, and the typical value are :  $K_{IV}=2.5V/mA$ ,  $Gm_{ramp}=8\mu A/V$ ,  $C_{ramp}=6.5pF$ .

 $V_{\text{D}}$  is the offset of the constant on-time comparator, and its typical value is 0.63V. It is recommended to design  $V_{\text{COMP}}=2$  to 3V. If the COMP voltage is over its recommended operating range (0.7 to 4.3V), output current regulation may be affected. Thus, the resistors  $R_{\text{ZCD1}}$  can be determined according to the above parameters.

#### **Minimum On-Time Setting**

The RT7306D limits a minimum on-time ( $t_{ON(MIN)}$ ) for each switching cycle. The  $t_{ON(MIN)}$  can be derived from the following equations.

$$tON(MIN) \times I_{ZCD\_SH} = 187.5p \cdot sec \cdot A (typ.)$$

Thus, RzcD1 can be determined by:

$$R_{ZCD1} = \frac{t_{ON(MIN)} \times V_{IN}}{187.5p} \times \frac{N_A}{N_P} \text{ (typ.)}$$

In addition, the current flowing out of ZCD pin must be lower than 2.5mA (typ.). Thus, the  $R_{ZCD1}$  is also determined by :

$$R_{ZCD1} > \frac{\sqrt{2} \cdot V_{AC(MAX)}}{2.5m} \times \frac{N_A}{N_P}$$

where the V<sub>AC(MAX)</sub> is maximum input AC voltage.

#### **Output Over-Voltage Protection Setting**

Output OVP is achieved by sensing the voltage on the auxiliary winging. It is recommended that output OV level ( $V_{OUT\_OVP}$ ) is set at 120% of nominal output voltage ( $V_{OUT}$ ). Thus,  $R_{ZCD1}$  and  $R_{ZCD2}$  can be determined by the equation as :

$$V_{OUT} \times \frac{N_A}{N_S} \times \frac{R_{ZCD2}}{R_{ZCD1} + R_{ZCD2}} \times 120\% = 3.2V(typ.)$$

## RICHTEK

#### **Adaptive Blanking Time**

When the MOSFET is turned off, the leakage inductance of the transformer and parasitic capacitance (Coss) of the MOSFET induce resonance waveform on the ZCD pin. The resonance waveform may make the controller false trigger the ZCD OVP, and it may cause the controller operate in unstable condition. As load increases, the resonance time also increases. It is recommended to add a 10pF to 47pF bypass capacitor, and it should be as close to ZCD pin as possible. The larger bypass capacitor may cause phase shift on ZCD waveform, so the MOSFET is not turned on at exact valley point.

To avoid the above issue, the RT7306D provides adaptive blanking time ( $t_{BK}$ ). It varies with the peak voltage of the CS pin ( $V_{CS\_PK}$ ), as shown by the following formula :

 $t_{BK} = 2\mu s + V_{CS} P_K \times 2\mu s/V$ (typ.)

#### **Thermal Considerations**

The junction temperature should never exceed the absolute maximum junction temperature  $T_{J(MAX)}$ , listed under Absolute Maximum Ratings, to avoid permanent damage to the device. The maximum allowable power dissipation depends on the thermal resistance of the IC package, the PCB layout, the rate of surrounding airflow, and the difference between the junction and ambient temperatures. The maximum power dissipation can be calculated using the following formula :

 $P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$ 

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction-to-ambient thermal resistance.

For continuous operation, the maximum operating junction temperature indicated under Recommended Operating Conditions is 125°C. The junction-to-ambient thermal resistance,  $\theta_{JA}$ , is highly package dependent. For a SOP-8 package, the thermal resistance,  $\theta_{JA}$ , is 206.9°C/W on a standard JEDEC low effective-thermal-conductivity two-layer test board. The maximum power dissipation at  $T_A = 25$ °C can be calculated as below :

 $P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (206.9^{\circ}C/W) = 0.48W$  for a SOP-8 package.

The maximum power dissipation depends on the operating ambient temperature for the fixed  $T_{J(MAX)}$  and the thermal resistance,  $\theta_{JA}$ . The derating curves in Figure 6 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

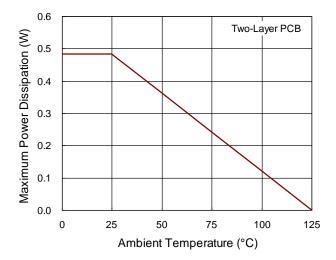


Figure 6. Derating Curve of Maximum Power Dissipation

RICHTEK

## RT7306D

#### **Layout Considerations**

A proper PCB layout can abate unknown noise interference and EMI issue in the switching power supply. Please refer to the guidelines when designing a PCB layout for switching power supply:

- ▶ The current path(1) from input capacitor, transformer, MOSFET, R<sub>CS</sub> return to input capacitor is a high frequency current loop. The path(2) from GD pin, MOSFET, R<sub>CS</sub> return to the ground of the IC is also a high frequency current loop. They must be as short as possible to decrease noise coupling and kept a space to other low voltage traces, such as IC control circuit paths, especially. Besides, the path(3) between MOSFET ground(b) and IC ground(d) is recommended to be as short as possible, too.
- ► The path(4) from RCD snubber circuit to MOSFET is a high switching loop. Keep it as small as possible.

- The path(5) from input capacitor to HV pin is a high voltage loop. Keep a space from path(5) to other low voltage traces.
- ▶ It is good for reducing noise, output ripple and EMI issue to separate ground traces of input capacitor(a), MOSFET(b), auxiliary winding(c) and IC control circuit(d). Finally, connect them together on input capacitor ground(a). The areas of these ground traces should be kept large.
- ▶ To minimize parasitic trace inductance and EMI, minimize the area of the loop connecting the secondary winding, the output diode, and the output filter capacitor. In addition, apply sufficient copper area at the anode and cathode terminal of the diode for heat-sinking. It is recommended to apply a larger area at the quiet cathode terminal. A large anode area will induce high-frequency radiated EMI.

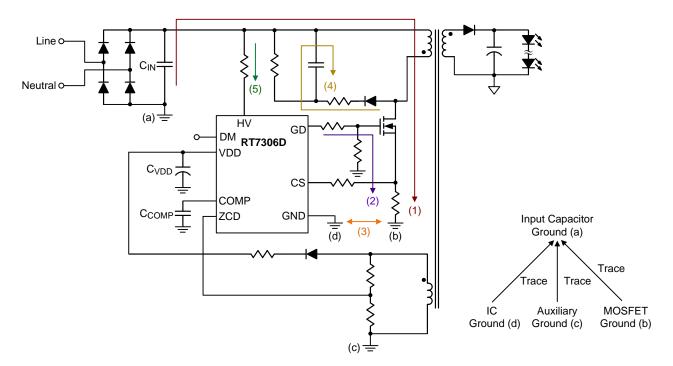
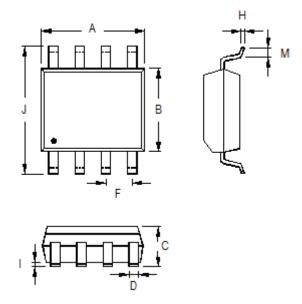


Figure 7. PCB Layout Guide



## **Outline Dimension**

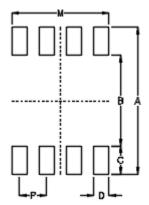


0	Dimensions I	n Millimeters	Dimensions In Inches			
Symbol	Min	Max	Min	Max		
А	4.801	5.004	0.189	0.197		
В	3.810	3.988	0.150	0.157		
С	1.346	1.753	0.053	0.069		
D	0.330	0.508	0.013	0.020		
F	1.194	1.346	0.047	0.053		
Н	0.170	0.254	0.007	0.010		
I	0.050	0.254	0.002	0.010		
J	5.791	6.200	0.228	0.244		
М	0.400	1.270	0.016	0.050		

8-Lead SOP Plastic Package



## **Footprint Information**



Dookogo	Number of Pin	Footprint Dimension (mm)					Toloropoo	
Package Nun	Number of Pin	Р	Α	В	С	D	М	Tolerance
SOP-8	8	1.27	6.80	4.20	1.30	0.70	4.51	±0.10

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Tel: (8863)5526789

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