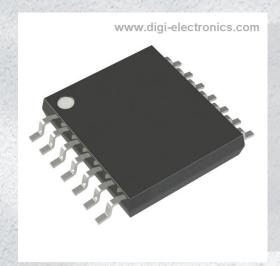


MCP6V14T-E/ST Datasheet



https://www.DiGi-Electronics.com

DiGi Electronics Part Number MCP6V14T-E/ST-DG

Manufacturer Microchip Technology

Manufacturer Product Number MCP6V14T-E/ST

Description IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

Detailed Description Zero-Drift Amplifier 4 Circuit Rail-to-Rail 14-TSSOP



Tel: +00 852-30501935

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Purchase and inquiry

Manufacturer Product Number:	Manufacturer:
MCP6V14T-E/ST	Microchip Technology
Series:	Product Status:
Zero-Drift	Active
Amplifier Type:	Number of Circuits:
Zero-Drift	4
Output Type:	Slew Rate:
Rail-to-Rail	0.03V/μs
Gain Bandwidth Product:	Current - Input Bias:
80 kHz	5 pA
Voltage - Input Offset:	Current - Supply:
8 μV	6.5µA (x4 Channels)
Current - Output / Channel:	Voltage - Supply Span (Min):
17 mA	1.6 V
Voltage - Supply Span (Max):	Operating Temperature:
5.5 V	-40°C ~ 125°C (TA)
Mounting Type:	Package / Case:
Surface Mount	14-TSSOP (0.173", 4.40mm Width)
Supplier Device Package:	Base Product Number:
14-TSSOP	MCP6V14

Environmental & Export classification

RoHS Status:	Moisture Sensitivity Level (MSL):
ROHS3 Compliant	1 (Unlimited)
REACH Status:	ECCN:
REACH Unaffected	EAR99
HTSUS:	

8542.33.0001



7.5 µA, 80 kHz Zero-Drift Op Amps

Features:

- · High DC Precision:
 - V_{OS} Drift: ±50 nV/°C (maximum)
 - V_{OS}: ±8 μV (maximum)
 - A_{OL} : 112 dB (minimum, V_{DD} = 5.5V)
 - PSRR: 118 dB (minimum, $V_{DD} = 5.5V$)
 - CMRR: 119 dB (minimum, $V_{DD} = 5.5V$)
 - E_{ni} : 2.1 μV_{P-P} (typical), f = 0.1 Hz to 10 Hz
 - E_{ni} : 0.67 μV_{P-P} (typical), f = 0.01 Hz to 1 Hz
- · Low Power and Supply Voltages:
 - I_O: 7.5 μA/amplifier (typical)
 - Wide Supply Voltage Range: 1.6V to 5.5V
- · Small Packages:
 - Singles in SC70, SOT-23
 - Duals in MSOP-8, 2×3 TDFN
 - Quads in TSSOP-14
- · Easy to Use:
 - Rail-to-Rail Input/Output
 - Gain Bandwidth Product: 80 kHz (typical)
 - Unity Gain Stable
- Extended Temperature Range: -40°C to +125°C

Typical Applications:

- · Portable Instrumentation
- · Sensor Conditioning
- · Temperature Measurement
- · DC Offset Correction
- · Medical Instrumentation

Design Aids:

- · SPICE Macro Models
- FilterLab[®] Software
- Microchip Advanced Part Selector (MAPS)
- · Analog Demonstration and Evaluation Boards
- · Application Notes

Related Parts:

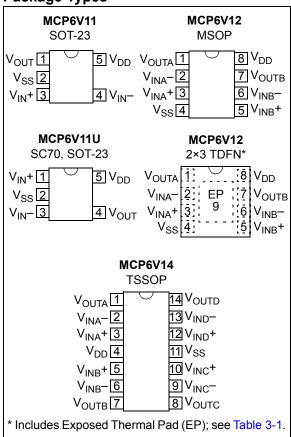
- MCP6V01/2/3: Auto-Zeroed, Spread Clock
- MCP6V06/7/8: Auto-Zeroed
- · MCP6V26/7/8: Auto-Zeroed, Low Noise
- MCP6V31/1U/2/4: Zero-Drift, Low Power

Description:

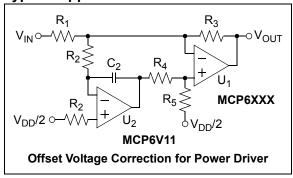
The Microchip Technology Inc. MCP6V11/1U/2/4 family of operational amplifiers provides input offset voltage correction for very low offset and offset drift. These are low-power devices, with a gain bandwidth product of 80 kHz (typical). They are unity gain stable, have virtually no 1/f noise, and have good Power Supply Rejection Ratio (PSRR) and Common Mode Rejection Ratio (CMRR). These products operate with a single supply voltage as low as 1.6V, while drawing 7.5 µA/amplifier (typical) of quiescent current.

The Microchip Technology Inc. MCP6V11/1U/2/4 op amps are offered in single (MCP6V11 and MCP6V11U), dual (MCP6V12) and quad (MCP6V14) packages. They were designed using an advanced CMOS process.

Package Types



Typical Application Circuit



1.0 ELECTRICAL CHARACTERISTICS

1.1 Absolute Maximum Ratings †

Note 1: See Section 4.2.1, Rail-to-Rail Inputs.

† Notice: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

1.2 Specifications

TABLE 1-1: DC ELECTRICAL SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, $T_A = +25^{\circ}C$, $V_{DD} = +1.6V$ to +5.5V, $V_{SS} = GND$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 100 \text{ k}\Omega$ to V_L and $C_L = 20 \text{ pF}$ (refer to Figure 1-4 and Figure 1-5). **Parameters** Sym. Min. Тур. Max. Units **Conditions Input Offset** Input Offset Voltage V_{OS} -8 +8 μV $T_A = +25^{\circ}C$ nV/°C Input Offset Voltage Drift with +50 $T_A = -40 \text{ to } +125^{\circ}\text{C}$ -50 TC₁ Temperature (Linear Temp. Co.) (Note 1) nV/°C2 $T_A = -40 \text{ to } +125^{\circ}\text{C}$ Input Offset Voltage Quadratic TC₂ ±0.08 Temp. Co. Power Supply Rejection Ratio **PSRR** 118 135 dB **Input Bias Current and Impedance** Input Bias Current +5 ρA I_B +17 Input Bias Current across Temperature $T_A = +85^{\circ}C$ I_B Αg 0 +2.9 +5 nΑ $T_A = +125^{\circ}C$ I_B Input Offset Current ±50 I_{OS} Αg Input Offset Current across Temperature ±80 pΑ $T_A = +85^{\circ}C$ los ±0.4 $T_A = +125^{\circ}C$ -1 +1 nΑ los 10¹³||6 Common Mode Input Impedance Z_{CM} $\Omega || pF$ 10¹³||6 Differential Input Impedance Z_{DIFF} $\Omega || pF$

Note 1: For Design Guidance only; not tested.

2: Figure 2-18 shows how V_{CML} and V_{CMH} changed across temperature for the first production lot.

TABLE 1-1: DC ELECTRICAL SPECIFICATIONS (CONTINUED)

Electrical Characteristics: Unless otherwise indicated, $T_A = +25^{\circ}C$, $V_{DD} = +1.6V$ to +5.5V, $V_{SS} = GND$, $V_{CM} = V_{DD}/3$, $V_{OUT} = V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 100 \text{ k}\Omega$ to V_L and $C_L = 20 \text{ pF}$ (refer to Figure 1-4 and Figure 1-5). **Parameters** Sym. Units **Conditions** Min. Typ. Max. **Common Mode** Common Mode V_{CML} $V_{SS} - 0.15$ ٧ (Note 2) Input Voltage Range Low Common Mode V_{CMH} $V_{DD} + 0.2$ ٧ (Note 2) Input Voltage Range High Common Mode Rejection Ratio **CMRR** 108 125 dB $V_{DD} = 1.6V,$ $V_{CM} = -0.15V \text{ to } 1.8V$ (Note 2) **CMRR** 119 135 dB $V_{DD} = 5.5V$ $V_{CM} = -0.15V \text{ to } 5.7V$ (Note 2) **Open-Loop Gain** $V_{DD} = 1.6V,$ DC Open-Loop Gain (large signal) 100 120 dB A_{OL} $V_{OUT} = 0.3V \text{ to } 1.4V$ $V_{DD} = 5.5V,$ 112 135 dB AOL $V_{OUT} = 0.3V \text{ to } 5.3V$ Output Minimum Output Voltage Swing m۷ V_{OL} V_{SS} $V_{SS} + 14$ $V_{SS} + 45$ $R_L = 10 \text{ k}\Omega, G = +2,$ 0.5V input overdrive $V_{SS} + 1.4$ $R_1 = 100 \text{ k}\Omega, G = +2,$ V_{OL} mV 0.5V input overdrive $R_1 = 10 \text{ k}\Omega, G = +2,$ Maximum Output Voltage Swing V_{OH} $V_{DD} - 45$ $V_{DD} - 14$ V_{DD} mV 0.5V input overdrive V_{OH} $R_L = 100 \text{ k}\Omega, G = +2,$ $V_{DD} - 1.4$ mV 0.5V input overdrive **Output Short Circuit Current** ±5 mΑ $V_{DD} = 1.6V$ I_{SC} ±17 mΑ $V_{DD} = 5.5V$ I_{SC} **Power Supply** Supply Voltage V_{DD} 1.6 5.5 V Quiescent Current per amplifier 4 μΑ 7.5 11 $I_{\rm O} = 0$, MCP6V11/1U la I_O = 0, MCP6V12/14 3 6.5 11 POR Trip Voltage V_{POR} 0.9 1.5 ٧

Note 1: For Design Guidance only; not tested.

^{2:} Figure 2-18 shows how V_{CML} and V_{CMH} changed across temperature for the first production lot.

TABLE 1-2: AC ELECTRICAL SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to +5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, V_L = 100 kΩ to V_L and C_L = 20 pF (refer to **Figure 1-4** and **Figure 1-5**). Sym. Min. Units **Conditions Parameters** Тур. Max. **Amplifier AC Response** Gain Bandwidth Product **GBWP** kHz 80 Slew Rate SR 0.03 V/µs Phase Margin PM 70 G = +1**Amplifier Noise Response** Input Noise Voltage 0.67 f = 0.01 Hz to 1 Hz E_{ni} μV_{P-P} f = 0.1 Hz to 10 Hz E_{ni} 2.1 μV_{P-P} Input Noise Voltage Density e_{ni} 102 nV/\sqrt{Hz} f < 500 Hz Input Noise Current Density fA/√Hz 4 İni **Amplifier Distortion (Note 1)** Intermodulation Distortion (AC) **IMD** 50 μV_{PK} V_{CM} tone = 50 m V_{PK} at 100 Hz, G_N = 1 **Amplifier Step Response** Start Up Time 2 G = +1, 0.1% V_{OUT} settling (Note 2) t_{STR} ms Offset Correction Settling Time 300 G = +1, V_{IN} step of 2V, μs t_{STL} V_{OS} within 100 μV of its final value Output Overdrive Recovery Time 450 G = -10, ± 0.5 V input overdrive to $V_{DD}/2$, t_{ODR} μs V_{IN} 50% point to V_{OUT} 90% point (Note 3)

- **Note 1:** These parameters were characterized using the circuit in **Figure 1-6**. In **Figure 2-37** and **Figure 2-38**, there is an IMD tone at DC, a residual tone at 1 kHz and other IMD tones and clock tones.
 - 2: High gains behave differently; see Section 4.3.3, Offset at Power Up.
 - **3:** t_{ODR} includes some uncertainty due to clock edge timing.

TABLE 1-3: TEMPERATURE SPECIFICATIONS

Electrical Characteristics: Unless otherwise indicated, all limits are specified for: $V_{DD} = +1.6V$ to +5.5V,								
V_{SS} = GND.								
Parameters	Sym.	Min.	Тур.	Max.	Units	Conditions		
Temperature Ranges	Temperature Ranges							
Specified Temperature Range	T _A	-40	_	+125	°C			
Operating Temperature Range	T _A	-40	_	+125	°C	(Note 1)		
Storage Temperature Range	T _A	-65		+150	°C			
Thermal Package Resistances								
Thermal Resistance, 5L-SC-70	$\theta_{\sf JA}$	_	209	_	°C/W			
Thermal Resistance, 5L-SOT-23	$\theta_{\sf JA}$	_	201	_	°C/W			
Thermal Resistance, 8L-2×3 TDFN	θ_{JA}	_	53	_	°C/W			
Thermal Resistance, 8L-MSOP	θ_{JA}	_	211	_	°C/W			
Thermal Resistance, 14L-TSSOP	θ_{JA}	_	100	_	°C/W			

Note 1: Operation must not cause T_J to exceed Maximum Junction Temperature specification (+150°C).

1.3 Timing Diagrams

V_{DD} <u>0V</u> 1.6V 1.6V to 5.5V 1.001(V_{DD}/3) V_{OUT} 0.999(V_{DD}/3)

FIGURE 1-1: Amplifier Start Up.

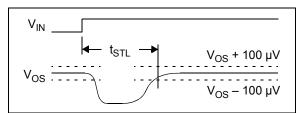


FIGURE 1-2: Offset Correction Settling Time.

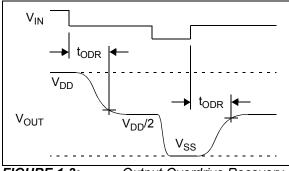


FIGURE 1-3: Output Overdrive Recovery.

1.4 Test Circuits

The circuits used for most DC and AC tests are shown in Figure 1-4 and Figure 1-5. Lay the bypass capacitors out as discussed in Section 4.3.10, Supply Bypassing and Filtering. R_{N} is equal to the parallel combination of R_{E} and R_{G} to minimize bias current effects.

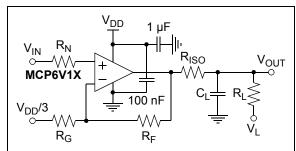


FIGURE 1-4: AC and DC Test Circuit for Most Non-Inverting Gain Conditions.

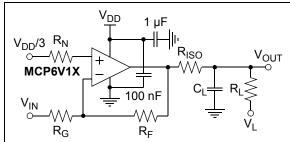


FIGURE 1-5: AC and DC Test Circuit for Most Inverting Gain Conditions.

The circuit in Figure 1-6 tests the input's dynamic behavior (i.e., IMD, t_{STR} , t_{STL} and t_{ODR}). The potentiometer balances the resistor network (V_{OUT} should equal V_{REF} at DC). The op amp's Common mode input voltage is $V_{CM} = V_{IN}/2$. The error at the input (V_{ERR}) appears at V_{OUT} with a noise gain of 10 V/V.

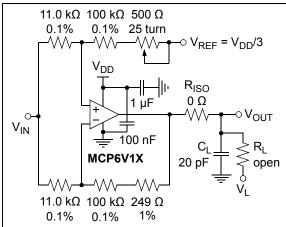


FIGURE 1-6: Test Circuit for Dynamic Input Behavior.

2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

2.1 DC Input Precision

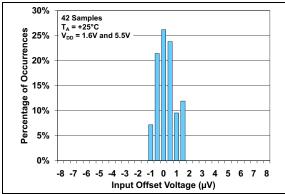


FIGURE 2-1: Input Offset Voltage.

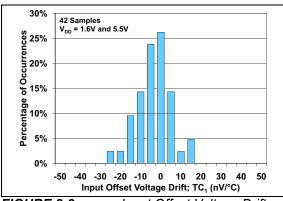


FIGURE 2-2: Input Offset Voltage Drift.

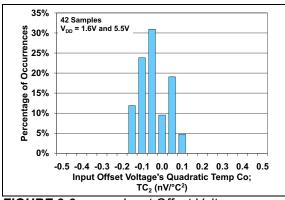


FIGURE 2-3: Input Offset Voltage Quadratic Temp. Co.

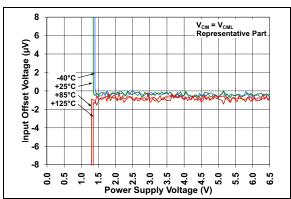


FIGURE 2-4: Input Offset Voltage vs. Power Supply Voltage with $V_{CM} = V_{CML}$.

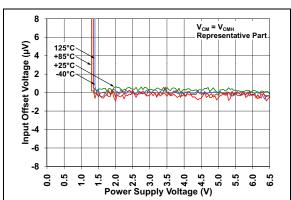


FIGURE 2-5: Input Offset Voltage vs. Power Supply Voltage with $V_{CM} = V_{CMH}$.

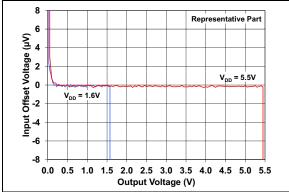


FIGURE 2-6: Input Offset Voltage vs. Output Voltage.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 100 \text{ k}\Omega$ to V_L and $C_L = 20 \text{ pF}$.

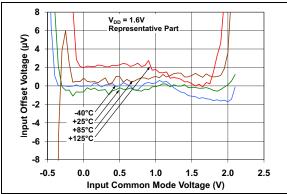


FIGURE 2-7: Input Offset Voltage vs. Common Mode Voltage with $V_{DD} = 1.6V$.

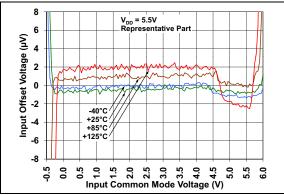
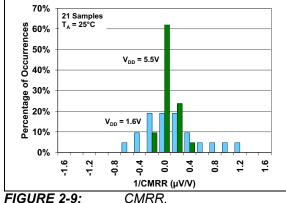


FIGURE 2-8: Input Offset Voltage vs. Common Mode Voltage with $V_{DD} = 5.5V$.



CMRR.

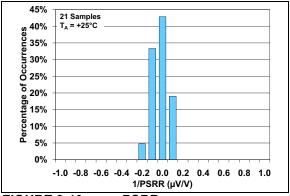


FIGURE 2-10: PSRR.

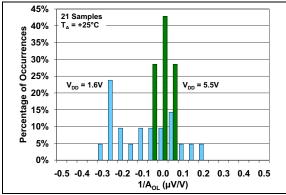


FIGURE 2-11: DC Open-Loop Gain.

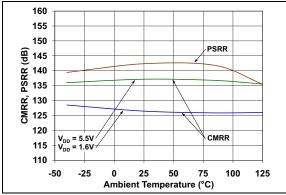


FIGURE 2-12: CMRR and PSRR vs. Ambient Temperature.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

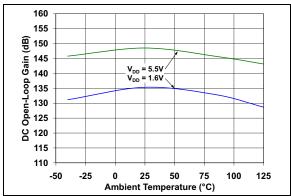


FIGURE 2-13: DC Open-Loop Gain vs. Ambient Temperature.

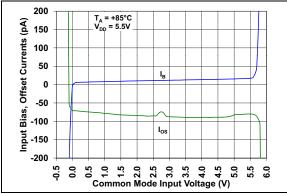


FIGURE 2-14: Input Bias and Offset Currents vs. Common Mode Input Voltage with $T_A = +85^{\circ}\text{C}$.

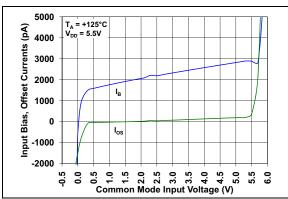


FIGURE 2-15: Input Bias and Offset Currents vs. Common Mode Input Voltage with $T_A = +125$ °C.

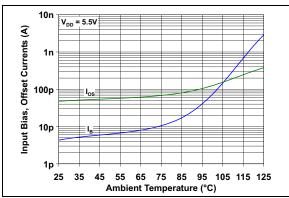


FIGURE 2-16: Input Bias and Offset Currents vs. Ambient Temperature with $V_{DD} = +5.5V$.

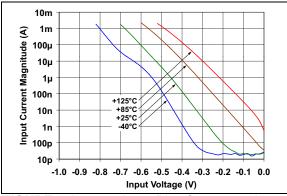


FIGURE 2-17: Input Bias Current vs. Input Voltage (below V_{SS}).

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, $V_L = V_{DD}/2$, $R_L = 100 \text{ k}\Omega$ to V_L and $C_L = 20 \text{ pF}$.

2.2 **Other DC Voltages and Currents**

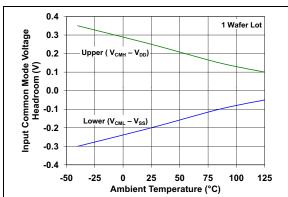
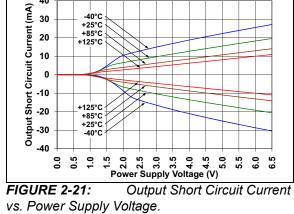
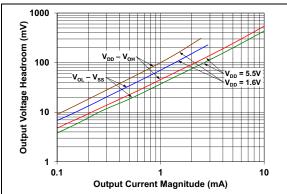


FIGURE 2-18: Input Common Mode Voltage Headroom (Range) vs. Ambient Temperature.





Output Voltage Headroom FIGURE 2-19: vs. Output Current.

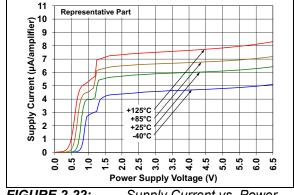


FIGURE 2-22: Supply Current vs. Power Supply Voltage.

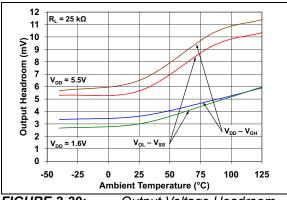


FIGURE 2-20: Output Voltage Headroom vs. Ambient Temperature.

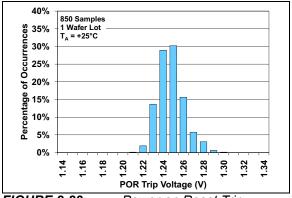


FIGURE 2-23: Power-on Reset Trip Voltage.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

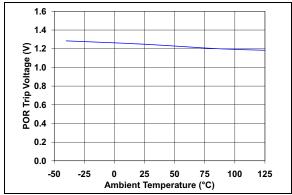


FIGURE 2-24: Power-on Reset Voltage vs. Ambient Temperature.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

2.3 Frequency Response

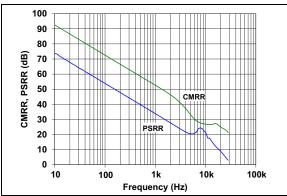


FIGURE 2-25:

CMRR and PSRR vs.



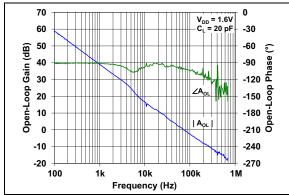


FIGURE 2-26: Open-Loop Gain vs. Frequency with $V_{DD} = 1.6V$.

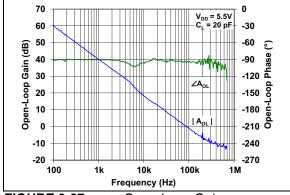


FIGURE 2-27: Open-Loop Gain vs. Frequency with $V_{DD} = 5.5V$.

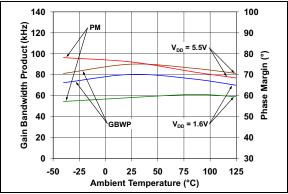


FIGURE 2-28: Gain Bandwidth Product and Phase Margin vs. Ambient Temperature.

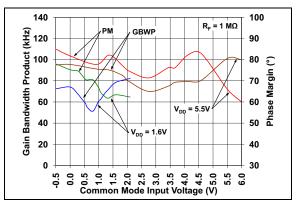


FIGURE 2-29: Gain Bandwidth Product and Phase Margin vs. Common Mode Input Voltage.

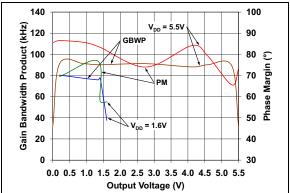


FIGURE 2-30: Gain Bandwidth Product and Phase Margin vs. Output Voltage.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

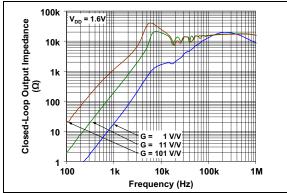


FIGURE 2-31: Closed-Loop Output Impedance vs. Frequency with $V_{DD} = 1.6V$.

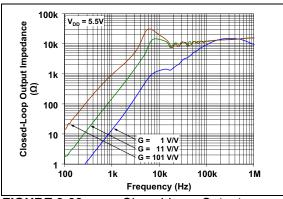


FIGURE 2-32: Closed-Loop Output Impedance vs. Frequency with $V_{DD} = 5.5V$.

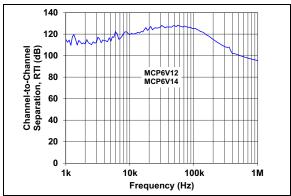


FIGURE 2-33: Channel-to-Channel Separation vs. Frequency.

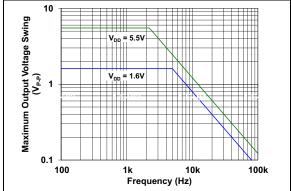


FIGURE 2-34: Maximum Output Voltage Swing vs. Frequency.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

2.4 Input Noise and Distortion

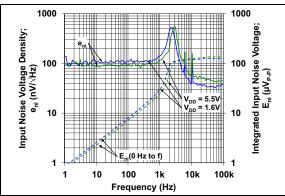


FIGURE 2-35: Input Noise Voltage Density and Integrated Input Noise Voltage vs. Frequency.

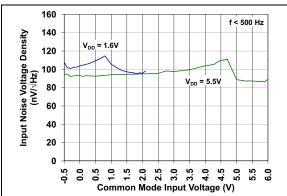


FIGURE 2-36: Input Noise Voltage Density vs. Input Common Mode Voltage.

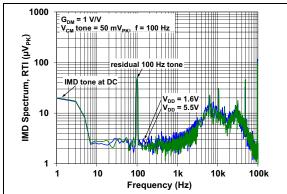


FIGURE 2-37: Inter-Modulation Distortion vs. Frequency with V_{CM} Disturbance (see Figure 1-6).

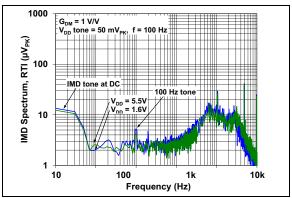


FIGURE 2-38: Inter-Modulation Distortion vs. Frequency with V_{DD} Disturbance (see Figure 1-6).

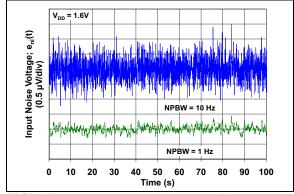


FIGURE 2-39: Input Noise vs. Time with 1 Hz and 10 Hz Filters and $V_{DD} = 1.6V$.

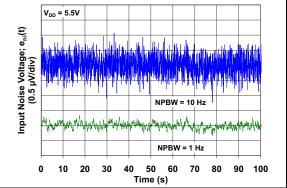


FIGURE 2-40: Input Noise vs. Time with 1 Hz and 10 Hz Filters and $V_{DD} = 5.5V$.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

2.5 Time Response

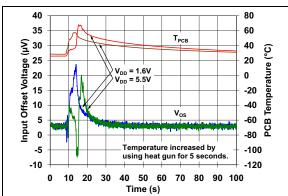


FIGURE 2-41: Input Offset Voltage vs. Time with Temperature Change.

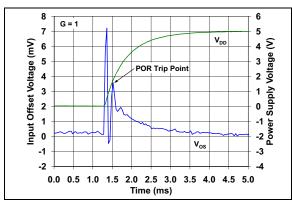


FIGURE 2-42: Input Offset Voltage vs. Time at Power Up.

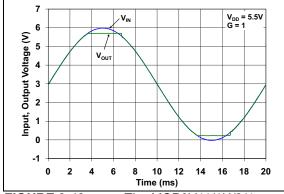


FIGURE 2-43: The MCP6V11/1U/2/4 Family Shows No Input Phase Reversal with Overdrive.

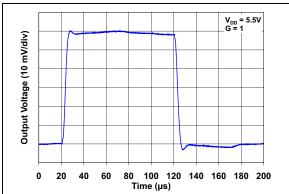


FIGURE 2-44: Non-inverting Small Signal Step Response.

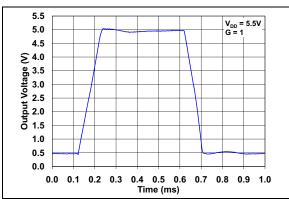


FIGURE 2-45: Non-inverting Large Signal Step Response.

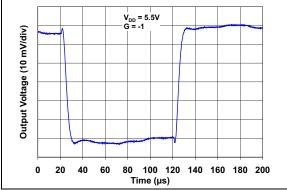


FIGURE 2-46: Inverting Small Signal Step Response.

Note: Unless otherwise indicated, T_A = +25°C, V_{DD} = +1.6V to 5.5V, V_{SS} = GND, V_{CM} = $V_{DD}/3$, V_{OUT} = $V_{DD}/2$, V_L = $V_{DD}/2$, R_L = 100 k Ω to V_L and C_L = 20 pF.

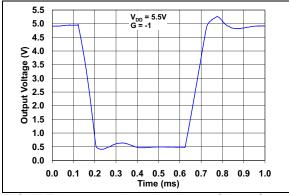


FIGURE 2-47: Inv. Response.

Inverting Large Signal Step

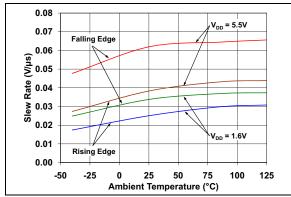


FIGURE 2-48: Temperature.

Slew Rate vs. Ambient

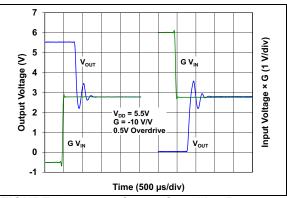


FIGURE 2-49: Output Overdrive Recovery vs. Time with G = -10 V/V.

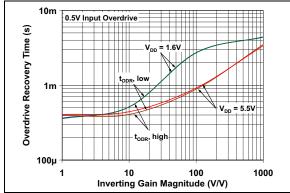


FIGURE 2-50: Output Overdrive Recovery Time vs. Inverting Gain.

3.0 PIN DESCRIPTIONS

Descriptions of the pins are listed in Table 3-1.

TABLE 3-1: PIN FUNCTION TABLE

MCP6V11	MCP6V11U	MCP6\	/12	MCP6V14		
SOT-23	SOT-23, SC-70	2×3 TDFN	MSOP	TSSOP	Symbol	Description
1	4	1	1	1	V _{OUT} , V _{OUTA}	Output (Op Amp A)
4	3	2	2	2	V _{IN} -, V _{INA} -	Inverting Input (Op Amp A)
3	1	3	3	3	V _{IN} +, V _{INA} +	Non-inverting Input (Op Amp A)
5	5	8	8	4	V_{DD}	Positive Power Supply
_	_	5	5	5	V _{INB} +	Non-inverting Input (Op Amp B)
_	_	6	6	6	V _{INB} –	Inverting Input (Op Amp B)
_	_	7	7	7	V_{OUTB}	Output (Op Amp B)
_	_	_	_	8	V _{OUTC}	Output (Op Amp C)
_	_	_	_	9	V _{INC} -	Inverting Input (Op Amp C)
_	_	_	_	10	V _{INC} +	Non-inverting Input (Op Amp C)
2	2	4	4	11	V_{SS}	Negative Power Supply
_	_	_	_	12	V _{IND} +	Non-inverting Input (Op Amp D)
	_			13	V _{IND} -	Inverting Input (Op Amp D)
_	_	_	_	14	V _{OUTD}	Output (Op Amp D)
_	_	9	_	_	EP	Exposed Thermal Pad (EP); must be connected to V _{SS}

3.1 Analog Outputs

The analog output pins $(V_{\mbox{\scriptsize OUT}})$ are low-impedance voltage sources.

3.2 Analog Inputs

The non-inverting and inverting inputs $(V_{IN}^+, V_{IN}^-, \ldots)$ are high-impedance CMOS inputs with low bias currents.

3.3 Power Supply Pins

The positive power supply (V_{DD}) is 1.6V to 5.5V higher than the negative power supply (V_{SS}). For normal operation, the other pins are between V_{SS} and V_{DD} .

Typically, these parts are used in a single (positive) supply configuration. In this case, V_{SS} is connected to ground and V_{DD} is connected to the supply. V_{DD} will need bypass capacitors.

3.4 Exposed Thermal Pad (EP)

There is an internal connection between the exposed thermal pad (EP) and the V_{SS} pin; they must be connected to the same potential on the printed circuit board (PCB).

This pad can be connected to a PCB ground plane to provide a larger heat sink. This improves the package thermal resistance (θ_{JA}).

MCP6V14T-E/ST Microchip Technology IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

MCP6V11/1U/2/4

NOTES:

4.0 APPLICATIONS

The MCP6V11/1U/2/4 family of zero-drift op amps is manufactured using Microchip's state of the art CMOS process. It is designed for precision applications with requirements for small packages and low power. Its low supply voltage and low quiescent current make the MCP6V11/1U/2/4 devices ideal for battery-powered applications.

4.1 Overview of Zero-Drift Operation

Figure 4-1 shows a simplified diagram of the MCP6V11/1U/2/4 zero-drift op amps. This diagram will be used to explain how slow voltage errors are reduced in this architecture (much better V_{OS} , $\Delta V_{OS}/\Delta T_A$ (TC₁), CMRR, PSRR, A_{OL} and 1/f noise).

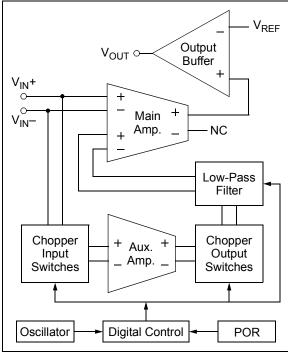


FIGURE 4-1: Simplified Zero-Drift Op Amp Functional Diagram.

4.1.1 BUILDING BLOCKS

The Main Amplifier is designed for high gain and bandwidth, with a differential topology. Its main input pair (+ and - pins at the top left) is used for the higher frequency portion of the input signal. Its auxiliary input pair (+ and - pins at the bottom left) is used for the low-frequency portion of the input signal and corrects the op amp's input offset voltage. Both inputs are added together internally.

The Auxiliary Amplifier, Chopper Input Switches and Chopper Output Switches provide a high DC gain to the input signal. DC errors are modulated to higher frequencies, while white noise is modulated to low frequency.

The Low-Pass Filter reduces high-frequency content, including harmonics of the Chopping Clock.

The Output Buffer drives external loads at the V_{OUT} pin (V_{RFF} is an internal reference voltage).

The Oscillator runs at f_{OSC1} = 50 kHz. Its output is divided by two, to produce the Chopping Clock rate of f_{CHOP} = 25 kHz.

The internal POR part starts the part in a known good state, protecting against power supply brown-outs.

The Digital Control block controls switching and POR events.

4.1.2 CHOPPING ACTION

Figure 4-2 shows the amplifier connections for the first phase of the Chopping Clock and Figure 4-3 shows them for the second phase. Its slow voltage errors alternate in polarity, making the average error small.

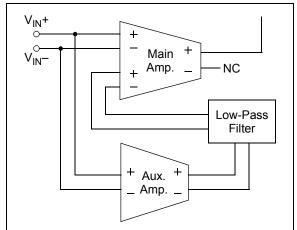


FIGURE 4-2: First Chopping Clock Phase; Equivalent Amplifier Diagram.

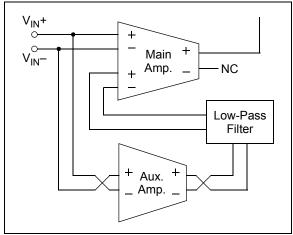


FIGURE 4-3: Second Chopping Clock Phase; Equivalent Amplifier Diagram.

4.1.3 INTERMODULATION DISTORTION (IMD)

These op amps will show intermodulation distortion (IMD) products when an AC signal is present.

The signal and clock can be decomposed into sine wave tones (Fourier series components). These tones interact with the zero-drift circuitry's nonlinear response to produce IMD tones at sum and difference frequencies. Each of the square wave clock's harmonics has a series of IMD tones centered on it. See Figure 2-37 and Figure 2-38.

4.2 Other Functional Blocks

4.2.1 RAIL-TO-RAIL INPUTS

The input stage of the MCP6V11/1U/2/4 op amps uses two differential CMOS input stages in parallel. One operates at low Common mode input voltage (V_{CM}, which is approximately equal to V_{IN}+ and V_{IN}- in normal operation) and the other at high V_{CM}. With this topology, the input operates with V_{CM} up to V_{DD} + 0.2V, and down to V_{SS} – 0.15V, at +25°C (see Figure 2-18). The input offset voltage (V_{OS}) is measured at V_{CM} = V_{SS} – 0.15V and V_{DD} + 0.2V to ensure proper operation.

The transition between the input stages occurs when $V_{CM} \approx V_{DD} - 0.9V$ (see Figure 2-7 and Figure 2-8). For the best distortion and gain linearity, with non-inverting gains, avoid this region of operation.

4.2.1.1 Phase Reversal

The input devices are designed to not exhibit phase inversion when the input pins exceed the supply voltages. Figure 2-43 shows an input voltage exceeding both supplies with no phase inversion.

4.2.1.2 Input Voltage Limits

In order to prevent damage and/or improper operation of these amplifiers, the circuit must limit the voltages at the input pins (see **Section 1.1 "Absolute Maximum Ratings †"**). This requirement is independent of the current limits discussed later on.

The ESD protection on the inputs can be depicted as shown in Figure 4-4. This structure was chosen to protect the input transistors against many (but not all) overvoltage conditions, and to minimize input bias current (I_B).

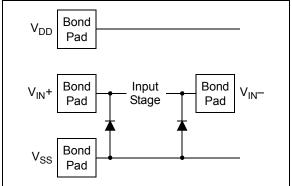


FIGURE 4-4: Simplified Analog Input ESD Structures.

The input ESD diodes clamp the inputs when they try to go more than one diode drop below V_{SS} . They also clamp any voltages well above V_{DD} ; their breakdown voltage is high enough to allow normal operation, but not low enough to protect against slow overvoltage (beyond V_{DD}) events. Very fast ESD events (that meet the spec) are limited so that damage does not occur.

In some applications, it may be necessary to prevent excessive voltages from reaching the op amp inputs; Figure 4-5 shows one approach to protecting these inputs. D_1 and D_2 may be small signal silicon diodes, Schottky diodes for lower clamping voltages or diode connected FETs for low leakage.

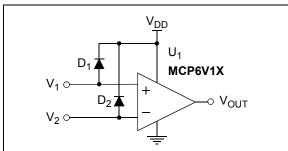


FIGURE 4-5: Protecting the Analog Inputs Against High Voltages.

4.2.1.3 Input Current Limits

In order to prevent damage and/or improper operation of these amplifiers, the circuit must limit the currents into the input pins (see **Section 1.1 "Absolute Maximum Ratings †"**). This requirement is independent of the voltage limits discussed previously.

Figure 4-6 shows one approach to protecting these inputs. The resistors R_1 and R_2 limit the possible current in or out of the input pins (and into D_1 and D_2). The diode currents will dump onto V_{DD} .

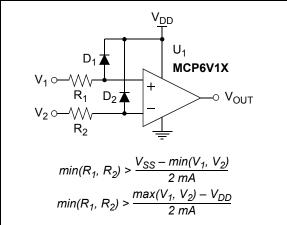


FIGURE 4-6: Protecting the Analog Inputs Against High Currents.

It is also possible to connect the diodes to the left of resistors R_1 and $\mathsf{R}_2.$ In this case, the currents through the diodes D_1 and D_2 need to be limited by some other mechanism. The resistors then serve as in-rush current limiters; the DC current into the input pins (V_{IN}+ and V_{IN}-) should be very small.

A significant amount of current can flow out of the inputs (through the ESD diodes) when the Common mode voltage (V_{CM}) is below ground (V_{SS}); see Figure 2-17.

4.2.2 RAIL-TO-RAIL OUTPUT

The output voltage range of the MCP6V11/1U/2/4 zero-drift op amps is $V_{DD}-20~\text{mV}$ (minimum) and $V_{SS}+20~\text{mV}$ (maximum) when $R_L=10~\text{k}\Omega$ is connected to $V_{DD}/2$ and $V_{DD}=5.5\text{V}$. Refer to Figure 2-19 and Figure 2-20 for more information.

This op amp is designed to drive light loads; use another amplifier to buffer the output from heavy loads.

4.3 Application Tips

4.3.1 INPUT OFFSET VOLTAGE OVER TEMPERATURE

Table 1-1 gives both the linear and quadratic temperature coefficients (TC₁ and TC₂) of input offset voltage. The input offset voltage, at any temperature in the specified range, can be calculated as follows:

EQUATION 4-1:

$$V_{OS}(T_A) = V_{OS} + TC_1 \Delta T + TC_2 \Delta T^2$$
Where:
$$\Delta T = T_A - 25^{\circ}C$$

V_{OS}(T_A) = input offset voltage at T_A

V_{OS} = input offset voltage at +25°C

TC₁ = linear temperature coefficient

TC₂ = quadratic temperature coefficient

4.3.2 DC GAIN PLOTS

Figures 2-9 to 2-11 are histograms of the reciprocals (in units of $\mu V/V)$ of CMRR, PSRR and $A_{OL},$ respectively. They represent the change in input offset voltage (V $_{OS}$) with a change in Common mode input voltage (V $_{CM}$), power supply voltage (V $_{DD}$) and output voltage (V $_{OUT}$).

The $1/A_{OL}$ histogram is centered near 0 μ V/V because the measurements are dominated by the op amp's input noise. The negative values shown represent noise and tester limitations, *not* unstable behavior. Production tests make multiple V_{OS} measurements, which validates an op amp's stability; an unstable part would show greater V_{OS} variability, or the output would stick at one of the supply rails.

4.3.3 OFFSET AT POWER UP

When these parts power up, the input offset (V_{OS}) starts at its uncorrected value (usually less than ± 5 mV). Circuits with high DC gain can cause the output to reach one of the two rails. In this case, the time to a valid output is delayed by an output overdrive time (like t_{ODR}), in addition to the start-up time (like t_{STR}).

It can be simple to avoid this extra start-up time. Reducing the gain is one method. Adding a capacitor across the feedback resistor (R_F) is another method.

4.3.4 SOURCE RESISTANCES

The input bias currents have two significant components; switching glitches that dominate at room temperature and below, and input ESD diode leakage currents that dominate at +85°C and above.

Make the resistances seen by the inputs small and equal. This minimizes the output offset caused by the input bias currents.

The inputs should see a resistance on the order of 10 Ω to 1 $k\Omega$ at high frequencies (i.e., above 1 MHz). This helps minimize the impact of switching glitches, which are very fast, on overall performance. In some cases, it may be necessary to add resistors in series with the inputs to achieve this improvement in performance.

Small input resistances may be needed for high gains. Without them, parasitic capacitances might cause positive feedback and instability.

4.3.5 SOURCE CAPACITANCE

The capacitances seen by the two inputs should be small. Large input capacitances and source resistances, together with high gain, can lead to positive feedback and instability.

4.3.6 CAPACITIVE LOADS

Driving large capacitive loads can cause stability problems for voltage feedback op amps. As the load capacitance increases, the feedback loop's phase margin decreases and the closed-loop bandwidth is reduced. This produces gain peaking in the frequency response, with overshoot and ringing in the step response. These zero-drift op amps have a different output impedance than most op amps, due to their unique topology.

When driving a capacitive load with these op amps, a series resistor at the output ($R_{\rm ISO}$ in Figure 4-7) improves the feedback loop's phase margin (stability) by making the output load resistive at higher frequencies. The bandwidth will be generally lower than the bandwidth with no capacitive load.

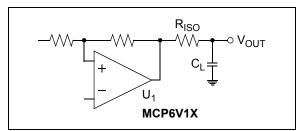


FIGURE 4-7: Output Resistor, R_{ISO}, Stabilizes Capacitive Loads.

Figure 4-8 gives recommended R_{ISO} values for different capacitive loads and gains. The x-axis is the load capacitance (C_L). The y-axis is the resistance (R_{ISO}).

 G_N is the circuit's noise gain. For non-inverting gains, G_N and the Signal Gain are equal. For inverting gains, G_N is 1+|Signal Gain| (e.g., -1 V/V gives $G_N = +2$ V/V).

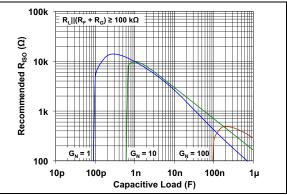


FIGURE 4-8: Recommended R_{ISO} Values for Capacitive Loads.

After selecting $R_{\rm ISO}$ for your circuit, double check the resulting frequency response peaking and step response overshoot. Modify $R_{\rm ISO}$'s value until the response is reasonable. Bench evaluation is helpful.

4.3.7 STABILIZING OUTPUT LOADS

This family of zero-drift op amps has an output impedance (Figure 2-31 and Figure 2-32) that has a double zero when the gain is low. This can cause a large phase shift in feedback networks that have low-impedance near the part's bandwidth. This large phase shift can cause stability problems.

Figure 4-9 shows that the load on the output is $(R_L + R_{ISO})||(R_F + R_G)$, where R_{ISO} is before the load (like Figure 4-7). This load needs to be large enough to maintain stability; it should be at least 10 k Ω .

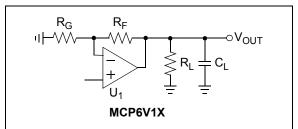


FIGURE 4-9: Output Load.

4.3.8 GAIN PEAKING

Figure 4-10 shows an op amp circuit that represents non-inverting amplifiers (V_M is a DC voltage and V_P is the input) or inverting amplifiers (V_P is a DC voltage and V_M is the input). The capacitances C_N and C_G represent the total capacitance at the input pins; they include the op amp's Common mode input capacitance (C_{CM}), board parasitic capacitance and any capacitor placed in parallel. The capacitance C_{FP} represents the parasitic capacitance coupling the output and non-inverting input pins.

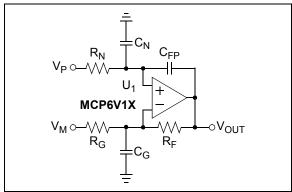


FIGURE 4-10: Amplifier with Parasitic Capacitance.

 C_G acts in parallel with R_G (except for a gain of +1 V/V), which causes an increase in gain at high frequencies. C_G also reduces the phase margin of the feedback loop, which becomes less stable. This effect can be reduced by either reducing C_G or $R_F || R_G$.

 C_N and R_N form a low-pass filter that affects the signal at V_P . This filter has a single real pole at $1/(2\pi R_N C_N)$.

The largest value of R_F that should be used depends on noise gain (see G_N in Section 4.3.6, Capacitive Loads), C_G and the open-loop gain's phase shift. An approximate limit for R_F is:

EQUATION 4-2:

$$R_F \leq (40~k\Omega) \times \frac{12~pF}{C_G} \times G_N^2$$

Some applications may modify these values to reduce either output loading or gain peaking (step response overshoot).

At high gains, R_N needs to be small, in order to prevent positive feedback and oscillations. Large C_N values can also help.

4.3.9 REDUCING UNDESIRED NOISE AND SIGNALS

Reduce undesired noise and signals with:

- · Low bandwidth signal filters:
 - Minimizes random analog noise
 - Reduces interfering signals
- · Good PCB layout techniques:
 - Minimizes crosstalk
 - Minimizes parasitic capacitances and inductances that interact with fast switching edges
- · Good power supply design:
 - Isolation from other parts
 - Filtering of interference on supply line(s)

4.3.10 SUPPLY BYPASSING AND FILTERING

With this family of operational amplifiers, the power supply pin (V_{DD} for single supply) should have a local bypass capacitor (i.e., 0.01 μF to 0.1 μF) within 2 mm of the pin for good high-frequency performance.

These parts also need a bulk capacitor (i.e., $1 \mu F$ or larger) within 100 mm to provide large, slow currents. This bulk capacitor can be shared with other low noise, analog parts.

In some cases, high-frequency power supply noise (e.g., switched mode power supplies) may cause undue intermodulation distortion, with a DC offset shift; this noise needs to be filtered. Adding a resistor into the supply connection can be helpful.

4.3.11 PCB DESIGN FOR DC PRECISION

In order to achieve DC precision on the order of $\pm 1~\mu V$, many physical errors need to be minimized. The design of the Printed Circuit Board (PCB), the wiring, and the thermal environment have a strong impact on the precision achieved. A poor PCB design can easily be more than 100 times worse than the MCP6V11/1U/2/4 op amps' minimum and maximum specifications.

4.3.11.1 PCB Layout

Any time two dissimilar metals are joined together, a temperature dependent voltage appears across the junction (the Seebeck or thermojunction effect). This effect is used in thermocouples to measure temperature. The following are examples of thermojunctions on a PCB:

- Components (resistors, op amps, ...) soldered to a copper pad
- · Wires mechanically attached to the PCB
- Jumpers
- · Solder joints
- · PCB vias

Typical thermojunctions have temperature to voltage conversion coefficients of 1 to 100 μ V/°C (sometimes higher).

Microchip's AN1258 ("Op Amp Precision Design: PCB Layout Techniques") contains in-depth information on PCB layout techniques that minimize thermojunction effects. It also discusses other effects, such as crosstalk, impedances, mechanical stresses and humidity.

4.3.11.2 Crosstalk

DC crosstalk causes offsets that appear as a larger input offset voltage. Common causes include:

- · Common mode noise (remote sensors)
- · Ground loops (current return paths)
- · Power supply coupling

Interference from the mains (usually 50 Hz or 60 Hz), and other AC sources, can also affect the DC performance. Nonlinear distortion can convert these signals to multiple tones, including a DC shift in voltage. When the signal is sampled by an ADC, these AC signals can also be aliased to DC, causing an apparent shift in offset.

To reduce interference:

- Keep traces and wires as short as possible
- Use shielding
- Use ground plane (at least a star ground)
- Place the input signal source near to the DUT
- Use good PCB layout techniques
- Use a separate power supply filter (bypass capacitors) for these zero-drift op amps

4.3.11.3 Miscellaneous Effects

Keep the resistances seen by the input pins as small and as near to equal as possible, to minimize biascurrent-related offsets.

Make the (trace) capacitances seen by the input pins small and equal. This is helpful in minimizing switching glitch-induced offset voltages.

Bending a coax cable with a radius that is too small causes a small voltage drop to appear on the center conductor (the triboelectric effect). Make sure the bending radius is large enough to keep the conductors and insulation in full contact.

Mechanical stresses can make some capacitor types (such as some ceramics) output small voltages. Use more appropriate capacitor types in the signal path and minimize mechanical stresses and vibration.

Humidity can cause electrochemical potential voltages to appear in a circuit. Proper PCB cleaning helps, as does the use of encapsulants.

4.4 Typical Applications

4.4.1 WHEATSTONE BRIDGE

Many sensors are configured as Wheatstone bridges. Strain gauges and pressure sensors are two common examples. These signals can be small and the Common mode noise large. Amplifier designs with high differential gain are desirable.

Figure 4-11 shows how to interface to a Wheatstone bridge with a minimum of components. Because the circuit is not symmetric, the ADC input is single ended, and there is a minimum of filtering; the CMRR is good enough for moderate Common mode noise.

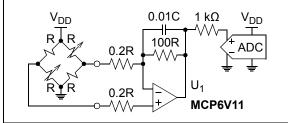


FIGURE 4-11: Simple Design.

4.4.2 RTD SENSOR

The ratiometric circuit in Figure 4-12 conditions a two-wire RTD, for applications with a limited temperature range. U_1 acts a difference amplifier, with a low frequency pole. The sensor's wiring resistance (R_W) is corrected in firmware. Failure (open) of the RTD is detected by an out-of-range voltage.

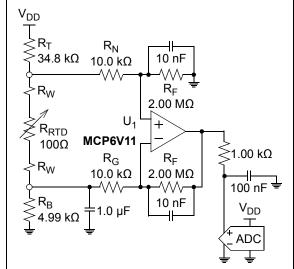


FIGURE 4-12: RTD Sensor.

4.4.3 OFFSET VOLTAGE CORRECTION

Figure 4-13 shows MCP6V11 (U_2) correcting the input offset voltage of another op amp (U_1). R_2 and C_2 integrate the offset error seen at U_1 's input; the integration needs to be slow enough to be stable (with the feedback provided by R_1 and R_3). R_4 and R_5 attenuate the integrator's output; this shifts the integrator pole down in frequency.

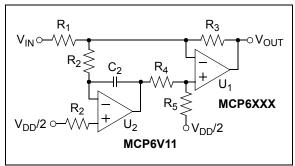


FIGURE 4-13: Offset Correction.

4.4.4 PRECISION COMPARATOR

Use high gain before a comparator to improve the latter's performance. Do not use MCP6V11/1U/2/4 as a comparator by itself; the V_{OS} correction circuitry does not operate properly without a feedback loop.

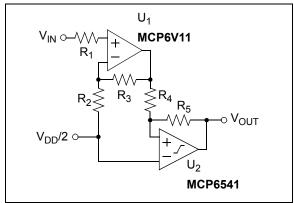


FIGURE 4-14: Precision Comparator.

NOTES:

5.0 DESIGN AIDS

Microchip provides the basic design aids needed for the MCP6V11/1U/2/4 family of op amps.

5.1 SPICE Macro Model

The latest SPICE macro model for the MCP6V11/1U/2/4 op amps is available on the Microchip web site at www.microchip.com. This model is intended to be an initial design tool that works well in the op amp's linear region of operation over the temperature range. See the model file for information on its capabilities.

Bench testing is a very important part of any design and cannot be replaced with simulations. Also, simulation results using this macro model need to be validated by comparing them to the data sheet specifications and characteristic curves.

5.2 FilterLab® Software

Microchip's FilterLab® software is an innovative software tool that simplifies analog active filter (using op amps) design. Available at no cost from the Microchip web site at www.microchip.com/filterlab, the FilterLab design tool provides full schematic diagrams of the filter circuit with component values. It also outputs the filter circuit in SPICE format, which can be used with the macro model to simulate actual filter performance.

5.3 Microchip Advanced Part Selector (MAPS)

MAPS is a software tool that helps efficiently identify Microchip devices that fit a particular design requirement. Available at no cost from the Microchip web site at www.microchip.com/maps, MAPS is an overall selection tool for Microchip's product portfolio that includes Analog, Memory, MCUs and DSCs. Using this tool, a customer can define a filter to sort features for a parametric search of devices and export side-by-side technical comparison reports. Helpful links are also provided for Data Sheets, Purchase and Sampling of Microchip parts.

5.4 Analog Demonstration and Evaluation Boards

Microchip offers a broad spectrum of Analog Demonstration and Evaluation Boards that are designed to help customers achieve faster time to market. For a complete listing of these boards and their corresponding user's guides and technical information, visit the Microchip web site at www.microchip.com/analog tools.

Some boards that are especially useful are:

- MCP6V01 Thermocouple Auto-Zeroed Reference Design (P/N MCP6V01RD-TCPL)
- MCP6XXX Amplifier Evaluation Board 1 (P/N DS51667)
- MCP6XXX Amplifier Evaluation Board 2 (P/N DS51668)
- MCP6XXX Amplifier Evaluation Board 3 (P/N DS51673)
- MCP6XXX Amplifier Evaluation Board 4 (P/N DS51681)
- Active Filter Demo Board Kit (P/N DS51614)
- 8-Pin SOIC/MSOP/TSSOP/DIP Evaluation Board (P/N SOIC8EV)
- 14-Pin SOIC/TSSOP/DIP Evaluation Board (P/N SOIC14EV)

5.5 Application Notes

The following Microchip Application Notes are available on the Microchip web site at www.microchip. com/appnotes and are recommended as supplemental reference resources.

ADN003: "Select the Right Operational Amplifier for your Filtering Circuits", DS21821

AN722: "Operational Amplifier Topologies and DC Specifications", DS00722

AN723: "Operational Amplifier AC Specifications and Applications", DS00723

AN884: "Driving Capacitive Loads With Op Amps", DS00884

AN990: "Analog Sensor Conditioning Circuits – An Overview", DS00990

AN1177: "Op Amp Precision Design: DC Errors", DS01177

AN1228: "Op Amp Precision Design: Random Noise", DS01228

AN1258: "Op Amp Precision Design: PCB Layout Techniques", DS01258

These Application Notes and others are listed in the design guide:

"Signal Chain Design Guide", DS21825

MCP6V14T-E/ST Microchip Technology IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

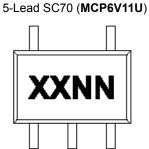
MCP6V11/1U/2/4

NOTES:

6.0 PACKAGING INFORMATION

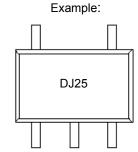
6.1 Package Marking Information



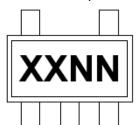


Device	Code		
MCP6V11UT-E/LT	DJNN		
N. 4 A P 4 5 1			

Note: Applies to 5-Lead SC-70.

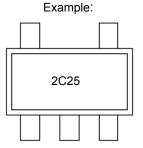


5-Lead SOT-23 (MCP6V11/1U)



Device	Code
MCP6V11T-E/OT	2CNN
MCP6V11UT-E/OT	2DNN

Note: Applies to 5-Lead SOT-23.



8-Lead MSOP (3x3 mm)(MCP6V12)







Legend: XX...X Customer-specific information

Y Year code (last digit of calendar year)
YY Year code (last 2 digits of calendar year)
WW Week code (week of January 1 is week '01')

NNN Alphanumeric traceability code

e3 Pb-free JEDEC® designator for Matte Tin (Sn)

This package is Pb-free. The Pb-free JEDEC designator (e3)

can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available

characters for customer-specific information.

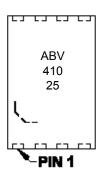
8-Lead TDFN (2x3x0.75 mm)(MCP6V12)



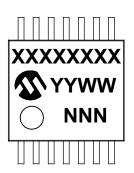
Device	Code
MCP6V12-E/MNY	ABV
MCP6V12T-E/MNY	ABV
1010101121	/ (D V

Note: Applies to 8-Lead 2x3 TDFN.

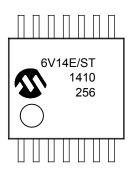
Example



14-Lead TSSOP (4.4 mm)(MCP6V14)

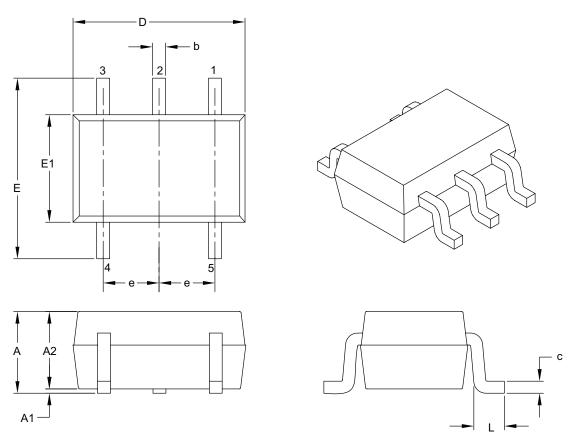


Example



5-Lead Plastic Small Outline Transistor (LT) [SC70]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS			
	Dimension Limits		NOM	MAX		
Number of Pins	N		5			
Pitch	е		0.65 BSC			
Overall Height	Α	0.80 – 1.1				
Molded Package Thickness	A2	0.80	_	1.00		
Standoff	A1	0.00	_	0.10		
Overall Width	E	1.80	2.10	2.40		
Molded Package Width	E1	1.15	1.25	1.35		
Overall Length	D	1.80	2.00	2.25		
Foot Length	L	0.10	0.20	0.46		
Lead Thickness	С	0.08	_	0.26		
Lead Width	b	0.15	_	0.40		

Notes:

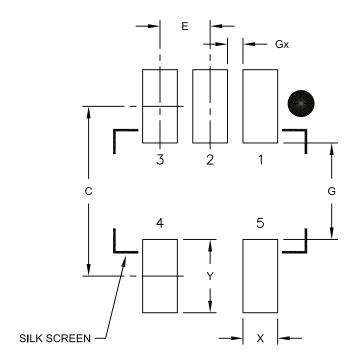
- 1. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.127 mm per side.
- 2. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-061B

5-Lead Plastic Small Outline Transistor (LT) [SC70]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	Units	I.	IILLIMETER	S
Dimension	Dimension Limits		NOM	MAX
Contact Pitch	Е		0.65 BSC	
Contact Pad Spacing	С	2.20		
Contact Pad Width	Х			0.45
Contact Pad Length	Υ			0.95
Distance Between Pads	G	1.25		
Distance Between Pads	Gx	0.20		

Notes:

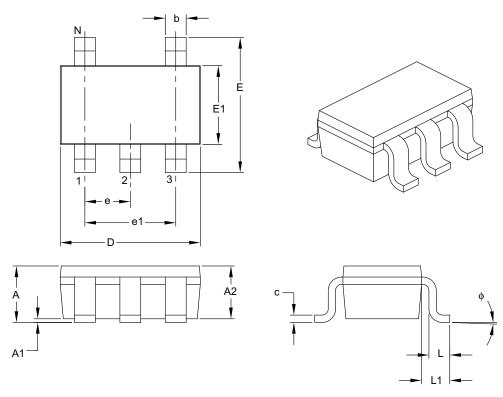
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2061A

5-Lead Plastic Small Outline Transistor (OT) [SOT-23]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS		
	Dimension Limits		NOM	MAX
Number of Pins	N		5	
Lead Pitch	е		0.95 BSC	
Outside Lead Pitch	e1		1.90 BSC	
Overall Height	Α	0.90	_	1.45
Molded Package Thickness	A2	0.89	_	1.30
Standoff	A1	0.00	_	0.15
Overall Width	E	2.20	_	3.20
Molded Package Width	E1	1.30	_	1.80
Overall Length	D	2.70	_	3.10
Foot Length	L	0.10	_	0.60
Footprint	L1	0.35	_	0.80
Foot Angle	ф	0°	-	30°
Lead Thickness	С	0.08	_	0.26
Lead Width	b	0.20	_	0.51

Notes:

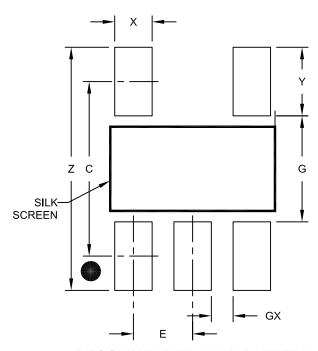
- 1. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.127 mm per side.
- 2. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-091B

5-Lead Plastic Small Outline Transistor (OT) [SOT-23]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension Limits		MIN	NOM	MAX
Contact Pitch	Е	E 0.95 BSC		
Contact Pad Spacing	С	2.80		
Contact Pad Width (X5)	Х			0.60
Contact Pad Length (X5)	Υ			1.10
Distance Between Pads	G	1.70		
Distance Between Pads	GX	0.35		
Overall Width	Z			3.90

Notes:

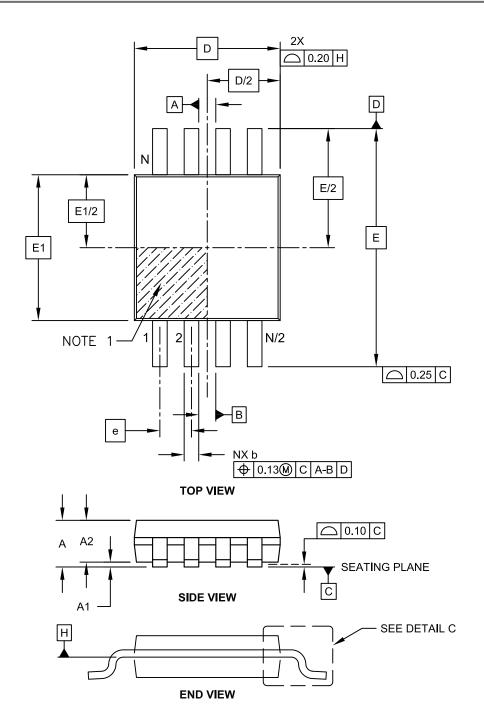
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2091A

8-Lead Plastic Micro Small Outline Package (MS) [MSOP]

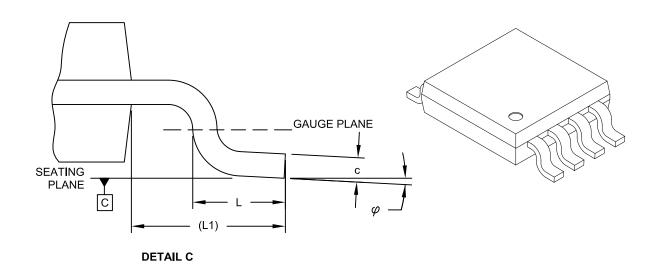
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-111C Sheet 1 of 2

8-Lead Plastic Micro Small Outline Package (MS) [MSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimension Limits		MIN	NOM	MAX	
Number of Pins	N	8			
Pitch	е	0.65 BSC			
Overall Height	Α	1.10			
Molded Package Thickness	A2	0.75 0.85 0.9			
Standoff	A1	0.00	-	0.15	
Overall Width	Е	4.90 BSC			
Molded Package Width	E1	3.00 BSC			
Overall Length	D	3.00 BSC			
Foot Length	Г	0.40	0.60	0.80	
Footprint	L1	0.95 REF			
Foot Angle	φ	0°	-	8°	
Lead Thickness	С	0.08 - 0.23		0.23	
Lead Width	b	0.22	-	0.40	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M.

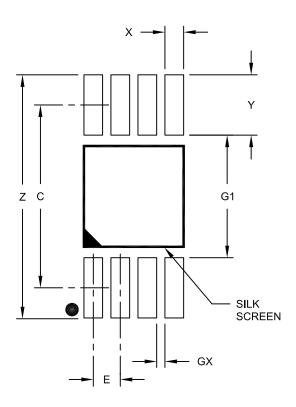
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-111C Sheet 2 of 2

8-Lead Plastic Micro Small Outline Package (MS) [MSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	С		4.40	
Overall Width	Z			5.85
Contact Pad Width (X8)	X1			0.45
Contact Pad Length (X8)	Y1			1.45
Distance Between Pads	G1	2.95		
Distance Between Pads	GX	0.20		

Notes:

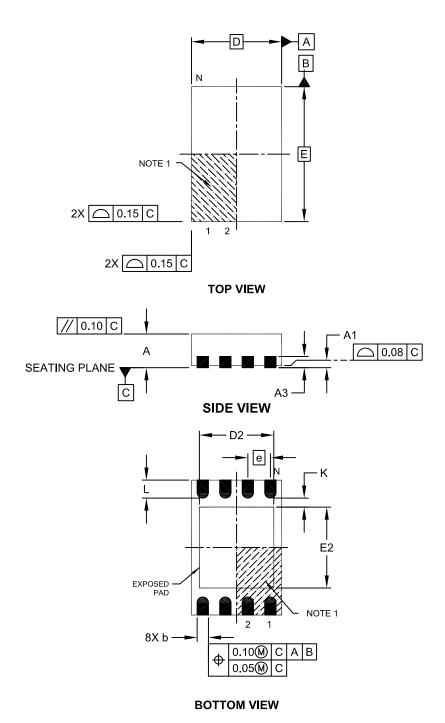
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2111A

^{1.} Dimensioning and tolerancing per ASME Y14.5M

8-Lead Plastic Dual Flat, No Lead Package (MN) - 2x3x0.75mm Body [TDFN]

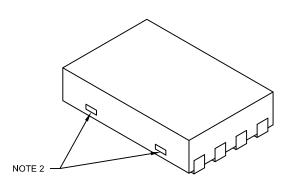
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing No. C04-129C Sheet 1 of 2

8-Lead Plastic Dual Flat, No Lead Package (MN) - 2x3x0.75mm Body [TDFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	8		
Pitch	е	0.50 BSC		
Overall Height	Α	0.70 0.75 0.80		
Standoff	A1	0.00 0.02 0.05		
Contact Thickness	A3	0.20 REF		
Overall Length	D	2.00 BSC		
Overall Width	Е	3.00 BSC		
Exposed Pad Length	D2	1.20 - 1.60		1.60
Exposed Pad Width	E2	1.20 - 1.60		1.60
Contact Width	b	0.20 0.25 0.30		0.30
Contact Length	L	0.25 0.30 0.45		
Contact-to-Exposed Pad	K	0.20	-	-

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package may have one or more exposed tie bars at ends.
- 3. Package is saw singulated
- 4. Dimensioning and tolerancing per ASME Y14.5M

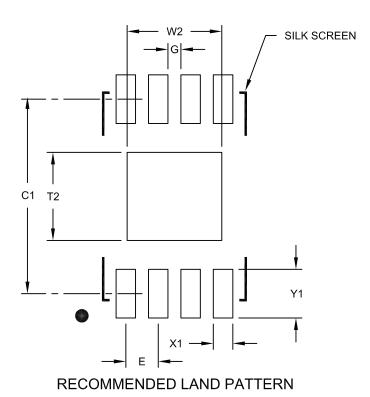
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-129C Sheet 2 of 2

8-Lead Plastic Dual Flat, No Lead Package (MN) – 2x3x0.75 mm Body [TDFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units **MILLIMETERS Dimension Limits** MIN NOM MAX Contact Pitch 0.50 BSC Ε Optional Center Pad Width W2 1.46 Optional Center Pad Length T2 1.36 Contact Pad Spacing C1 3.00 Contact Pad Width (X8) 0.30 X1

Υ1

G

0.20

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

Contact Pad Length (X8)

Distance Between Pads

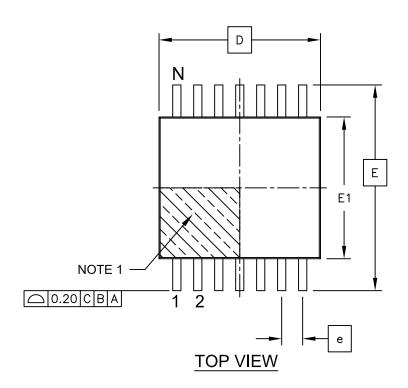
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

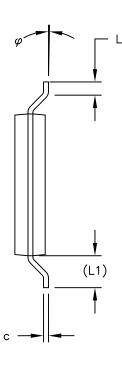
Microchip Technology Drawing No. C04-2129A

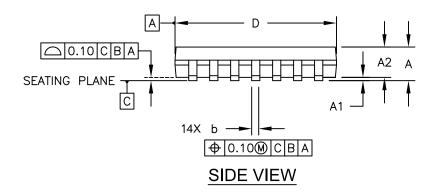
0.75

14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



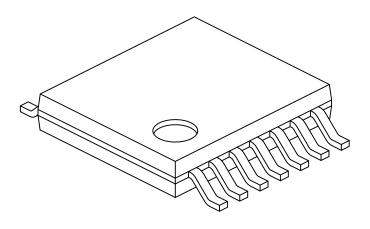




Microchip Technology Drawing C04-087C Sheet 1 of 2

14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Number of Pins	N	14			
Pitch	е	0.65 BSC			
Overall Height	Α	-	-	1.20	
Molded Package Thickness	A2	0.80	1.00	1.05	
Standoff	A1	0.05	-	0.15	
Overall Width	E	6.40 BSC			
Molded Package Width	E1	4.30	4.40	4.50	
Molded Package Length	D	4.90	5.00	5.10	
Foot Length	L	0.45	0.60	0.75	
Footprint	(L1)	1.00 REF			
Foot Angle	φ	0°	-	8°	
Lead Thickness	С	0.09	-	0.20	
Lead Width	b	0.19	-	0.30	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M

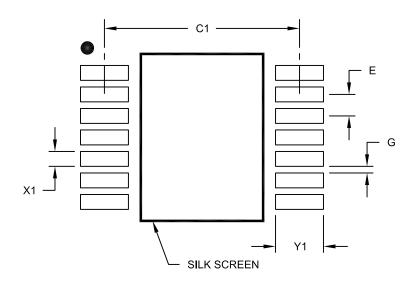
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-087C Sheet 2 of 2 $\,$

14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C1		5.90	
Contact Pad Width (X14)	X1			0.45
Contact Pad Length (X14)	Y1			1.45
Distance Between Pads	G	0.20		

Notes:

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2087A

^{1.} Dimensioning and tolerancing per ASME Y14.5M

MCP6V14T-E/ST Microchip Technology IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

MCP6V11/1U/2/4

NOTES:

APPENDIX A: REVISION HISTORY

Revision B (March 2014)

The following is the list of modifications:

- Added new devices to the family: MCP6V12 and MCP6V14, and the related information throughout the document.
- 2. Updated Table 1-3 with new packages' thermal resistances.
- 3. Updated Figures 1-6, 2-19 and 2-22 in **Section 2.0 "Typical Performance Curves"**. Added new Figure 2-33.
- 4. Updated Table 3-1 in Section 3.0 "Pin Descriptions" for the new devices.
- Updated markings and specification drawings in Section 6.0 "Packaging Information".
- 6. Updated Product Identification System.

Revision A (March 2012)

· Original Release of this Document.

MCP6V14T-E/ST Microchip Technology IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

MCP6V11/1U/2/4

NOTES:

PRODUCT IDENTIFICATION SYSTEM

 $\underline{\text{To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.}\\$

PART NO. [X] ⁽¹⁾ -X /XX		Examples:			
Device Tape and	I Reel Temperature Package Range	a)	MCP6V11T-E/OT:	Tape and Reel, Extended temperature, 5LD SOT-23 package	
Device:	MCP6V11T: Single Op Amp (Tape and Reel) (SOT-23) MCP6V11UT: Single Op Amp (Tape and Reel) (SC-70, SOT-23)	a)	MCP6V11UT-E/LT:	Tape and Reel Extended temperature, 5LD SC70 package	
	MCP6V12: Dual Op Amp (MSOP, 2x3 TDFN) MCP6V12T: Dual Op Amp (Tape and Reel) (MSOP, 2x3 TDFN)	b)	MCP6V11UT-E/OT:	Tape and Reel, Extended temperature, 5LD SOT-23 package	
	MCP6V14: Quad Op Amp (TSSOP) MCP6V14T: Quad Op Amp (Tape and Reel) (TSSOP)	a)	MCP6V12-E/MS:	Extended temperature, 8LD MSOP package	
Temperature Range:	E = -40°C to +125°C (Extended)	b)	MCP6V12T-E/MS:	Tape and Reel, Extended temperature, 8LD MSOP package	
Package:	LT = Plastic Small Outline Transistor, 5-lead OT = Plastic Small Outline Transistor, 5-lead MNY* = Plastic Dual Flat, No-Lead - 2×3×0.75 mm Body, 8-lead	c)	MCP6V12T-E/MNY:	Tape and Reel, Extended temperature, 8LD 2x3 TDFN package	
	MS = Plastic Micro Small Outline, 8-lead ST = Plastic Thin Shrink Small Outline - 4.4 mm	a)	MCP6V14-E/ST:	Extended temperature, 14LD TSSOP package	
	Body, 14-lead * Y = Nickel palladium gold manufacturing designator. Only available on the TDFN package.	b)	MCP6V14T-E/ST:	Tape and Reel Extended temperature, 14LD TSSOP package	
	, Ç	Note	catalog part nu fier is used for printed on the your Microchip	identifier only appears in the imber description. This identi- ordering purposes and is not device package. Check with Sales Office for package the Tape and Reel option.	

MCP6V14T-E/ST Microchip Technology IC OPAMP ZER-DRIFT 4CIRC 14TSSOP

MCP6V11/1U/2/4

NOTES:

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