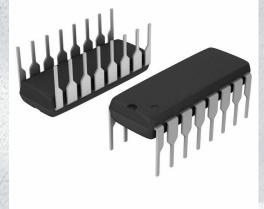


CD4046BCN Datasheet

www.digi-electronics.com



DiGi Electronics Part Number

Manufacturer

Manufacturer Product Number

Description

Detailed Description

CD4046BCN-DG

onsemi

CD4046BCN

IC PHASE LOCK LOOP 16DIP

Phase Lock Loop (PLL) IC 1.6MHz 1 16-DIP (0.300", 7.62mm)

https://www.DiGi-Electronics.com



Tel: +00 852-30501935

RFQ Email: Info@DiGi-Electronics.com

DiGi is a global authorized distributor of electronic components.



Purchase and inquiry

Manufacturer Product Number:	Manufacturer:
CD4046BCN	onsemi
Series:	Product Status:
	Obsolete
DiGi-Electronics Programmable:	Туре:
Not Verified	Phase Lock Loop (PLL)
PLL:	Input:
No	СМОЅ
Output:	Number of Circuits:
CMOS	1
Ratio - Input:Output:	Differential - Input:Output:
1:2	No/No
Frequency - Max:	Divider/Multiplier:
1.6MHz	No/No
Voltage - Supply:	Operating Temperature:
3V ~ 15V	-55°C ~ 125°C
Mounting Type:	Package / Case:
Through Hole	16-DIP (0.300", 7.62mm)
Supplier Device Package:	Base Product Number:
16-PDIP	CD4046

Environmental & Export classification

Moisture Sensitivity Level (MSL):
1 (Unlimited)
ECCN:
EAR99

REACH Status:
REACH Unaffected
HTSUS:
8542.39.0001

FAIRCHILD

SEMICONDUCTOR

CD4046BC Micropower Phase-Locked Loop

General Description

The CD4046BC micropower phase-locked loop (PLL) consists of a low power, linear, voltage-controlled oscillator (VCO), a source follower, a zener diode, and two phase comparators. The two phase comparators have a common signal input and a common comparator input. The signal input can be directly coupled for a large voltage signal, or capacitively coupled to the self-biasing amplifier at the signal input for a small voltage signal.

Phase comparator I, an exclusive OR gate, provides a digital error signal (phase comp. I Out) and maintains 90° phase shifts at the VCO center frequency. Between signal input and comparator input (both at 50% duty cycle), it may lock onto the signal input frequencies that are close to harmonics of the VCO center frequency.

Phase comparator II is an edge-controlled digital memory network. It provides a digital error signal (phase comp. II Out) and lock-in signal (phase pulses) to indicate a locked condition and maintains a 0° phase shift between signal input and comparator input.

The linear voltage-controlled oscillator (VCO) produces an output signal (VCO Out) whose frequency is determined by the voltage at the VCO_{IN} input, and the capacitor and resistors connected to pin C1_A, C1_B, R1 and R2.

The source follower output of the VCO_{IN} (demodulator Out) is used with an external resistor of 10 k Ω or more.

The INHIBIT input, when high, disables the VCO and source follower to minimize standby power consumption. The zener diode is provided for power supply regulation, if necessary.

. Features

- Wide supply voltage range: 3.0V to 18V
- Low dynamic power consumption: $70 \,\mu\text{W}$ (typ.)
- at $f_o = 10 \text{ kHz}$, $V_{DD} = 5V$

October 1987

Revised March 2002

- VCO frequency: 1.3 MHz (typ.) at V_{DD} = 10V
 Low frequency drift: 0.06%/°C at V_{DD} = 10V with temperature
- High VCO linearity: 1% (typ.)

Applications

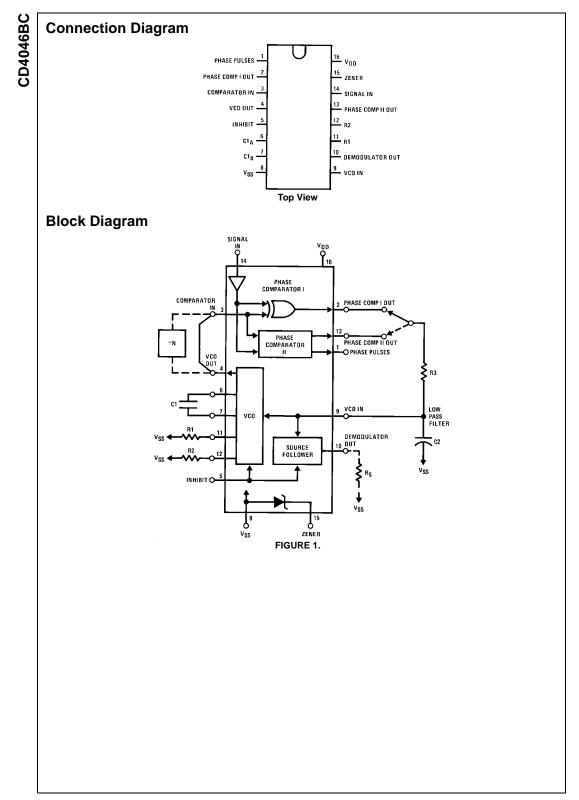
- FM demodulator and modulator
- Frequency synthesis and multiplication
- Frequency discrimination
- Data synchronization and conditioning
- Voltage-to-frequency conversion
- Tone decoding
- FSK modulation
- · Motor speed control

Ordering Code:

Order Number	Package Number	Package Description
CD4046BCM	M16A	16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow
CD4046BCN	N16E	16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300" Wide

Devices also available in Tape and Reel. Specify by appending the suffix letter "X" to the ordering code.

© 2002 Fairchild Semiconductor Corporation DS005968



Absolute Maximum Ratings(Note 1) (Note 2)

Recommended Operating Conditions (Note 2)

DC Supply Voltage (V _{DD}) Input Voltage (V _{IN})	–0.5 to +18 V _{DC} –0.5 to V _{DD} +0.5 V _{DC}
Storage Temperature Range (T _S)	-65°C to +150°C
Power Dissipation (P _D)	
Dual-In-Line	700 mW
Small Outline	500 mW
Lead Temperature (T _L)	
(Soldering, 10 seconds)	260°C

DC Supply Voltage (V_{DD}) Input Voltage (VIN)

0 to $V_{DD} V_{DC}$

CD4046BC

3 to 15 V_DC

Operating Temperature Range (T_A) $-55^{\circ}C$ to $+125^{\circ}C$ Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Recom-

mended Operating Conditions" and "Electrical Characteristics" provides conditions for actual device operation.

Note 2: $V_{SS} = 0V$ unless otherwise specified.

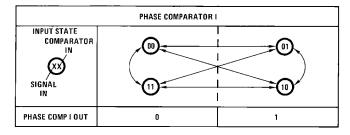
		0 14	–55°C			+25°C		+12	5°C	
Symbol	Parameter	Conditions	Min	Max	Min	Тур	Max	Min	Max	Unit
I _{DD}	Quiescent Device Current	$Pin 5 = V_{DD,} Pin 14 = V_{DD,}$								
		Pin 3, 9 = V _{SS}								
		$V_{DD} = 5V$		5		0.005	5		150	
		$V_{DD} = 10V$		10		0.01	10		300	μA
		$V_{DD} = 15V$		20		0.015	20		600	
		Pin 5 = V _{DD} , Pin 14 = Open,								
		Pin 3, 9 = V _{SS}								
		$V_{DD} = 5V$		45		5	35		185	
		$V_{DD} = 10V$		450		20	350		650	μA
		$V_{DD} = 15V$		1200		50	900		1500	
V _{OL}	LOW Level Output Voltage	$V_{DD} = 5V$		0.05		0	0.05		0.05	
		$V_{DD} = 10V$		0.05		0	0.05		0.05	V
		$V_{DD} = 15V$		0.05		0	0.05		0.05	
V _{ОН}	HIGH Level Output Voltage	$V_{DD} = 5V$	4.95		4.95	5		4.95		
		$V_{DD} = 10V$	9.95		9.95	10		9.95		V
		$V_{DD} = 15V$	14.95		14.95	15		14.95		
V _{IL}	LOW Level Input Voltage	$V_{DD} = 5V, V_{O} = 0.5V \text{ or } 4.5V$		1.5		2.25	1.5		1.5	
	Comparator and Signal In	$V_{DD} = 10V$, $V_O = 1V$ or $9V$		3.0		4.5	3.0		3.0	V
		V_{DD} = 15V, V_{O} = 1.5V or 13.5V		4.0		6.25	4.0		4.0	
VIH	HIGH Level Input Voltage	$V_{DD} = 5V$, $V_O = 0.5V$ or 4.5V	3.5		3.5	2.75		3.5		
	Comparator and Signal In	$V_{DD} = 10V$, $V_O = 1V$ or $9V$	7.0		7.0	5.5		7.0		V
		V_{DD} = 15V, V_{O} = 1.5V or 13.5V	11.0		11.0	8.25		11.0		
I _{OL}	LOW Level Output Current	$V_{DD} = 5V, V_{O} = 0.4V$	0.64		0.51	0.88		0.36		
	(Note 4)	$V_{DD} = 10V, V_{O} = 0.5V$	1.6		1.3	2.25		0.9		mA
		$V_{DD} = 15V, V_{O} = 1.5V$	4.2		3.4	8.8		2.4		
I _{OH}	HIGH Level Output Current	$V_{DD} = 5V, V_{O} = 4.6V$	-0.64		-0.51	-0.88		-0.36		
	(Note 4)	$V_{DD} = 10V, V_{O} = 9.5V$	-1.6		-1.3	-2.25		-0.9		mA
		$V_{DD} = 15V, V_{O} = 13.5V$	-4.2		-3.4	-8.8		-2.4		
I _{IN}	Input Current	All Inputs Except Signal Input								
		$V_{DD} = 15V, V_{IN} = 0V$		-0.1		-10 ⁻⁵	-0.1		-1.0	μA
		$V_{DD}=15V,\ V_{IN}=15V$		0.1		10 ⁻⁵	0.1		1.0	μΛ
C _{IN}	Input Capacitance	Any Input (Note 3)							7.5	pF
Ρ _T	Total Power Dissipation	$f_o = 10 \text{ kHz}, \text{ R1} = 1 \text{ M}\Omega,$								
		$R2=\infty, VCO_{IN}=V_{CC}/2$								
		$V_{DD} = 5V$				0.07				
		$V_{DD} = 10V$				0.6				mW
		$V_{DD} = 15V$				2.4				

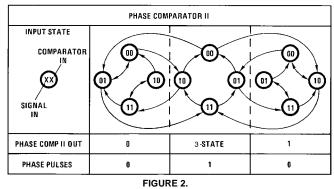
Note 4: $I_{\mbox{OH}}$ and $I_{\mbox{OL}}$ are tested one output at a time.

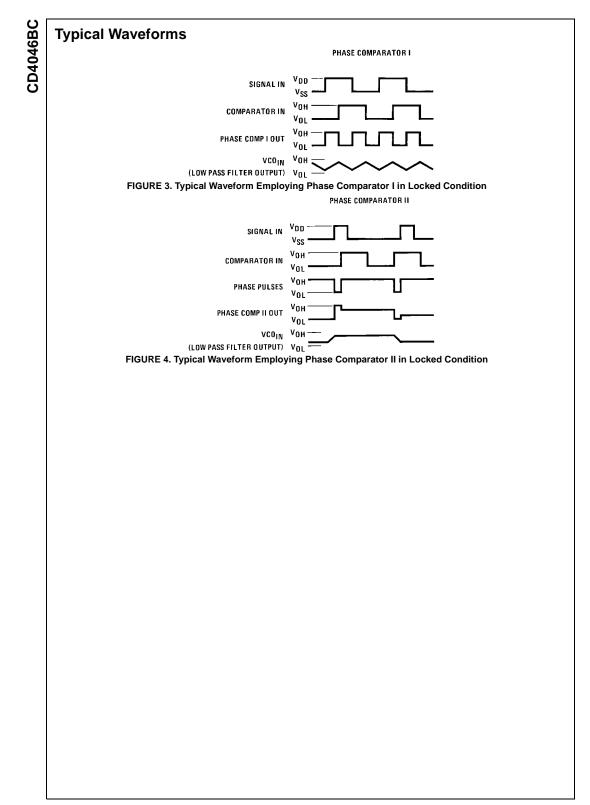
f _{MAX} Maximur Linearity Tempera No Fre Frequent VCO _{IN} Input Re VCO Output D	ing Current um Operating Frequency ty rature-Frequency Stability requency Offset, $f_{MIN} = 0$ ncy Offset, $f_{MIN} \neq 0$		0.4 0.6 1.0	20 90 200 0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08 0.015–0.03		MH %
f _{MAX} Maximur f _{MAX} Maximur Linearity Tempera No Fre Frequent VCO VCO Output D t _{THL} VCO Output D	um Operating Frequency ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\begin{array}{c} R2 = \infty, VCO_{IN} = V_{CC}/2 \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ C1 = 50 pF, R1 = 10 k\Omega, \\ R2 = \infty, VCO_{IN} = V_{DD} \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 k\Omega, V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 10 k\Omega, V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 10 M\Omega, V_{DD} = 15V \\ \hline \\ \hline \\ & \%''C < 5c1/f. V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \hline \\ & V_{DD} = 15V \\ \hline \end{array}$	0.6	90 200 0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		MH %
Linearity Linearity Tempera No Fre VCO _{IN} Input Re VCO VCO VCO Utput D t _{THL}	ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\begin{array}{c} V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ C1 = 50 pF, R1 = 10 k\Omega, \\ R2 = \infty, VCO_{IN} = V_{DD} \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 k\Omega, V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 k\Omega, V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 M\Omega, V_{DD} = 15V \\ \hline \\ \\ & \%''C < 5c1/f. V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \hline \\ & V_{DD} = 15V \\ \hline \\ \end{array}$	0.6	90 200 0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		
Linearity Linearity Tempera No Fre VCO _{IN} Input Re VCO VCO VCO Utput D t _{THL}	ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\begin{array}{c} V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ C1 = 50 \ pF, \ R1 = 10 \ k\Omega, \\ R2 = \infty, \ VCO_{IN} = V_{DD} \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ k\Omega, \ V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \ k\Omega, \ V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ M\Omega, \ V_{DD} = 15V \\ \hline \\ \begin{array}{c} \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \hline \\ V_{DD} = 15V \\ \hline \\ V_{DD} = 5V \\ V_{DD} = 5V \\ \hline \\ V_{DD} = 5V \\ \hline \end{array}$	0.6	90 200 0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		MH %
Linearity Linearity Tempera No Fre VCO _{IN} Input Re VCO VCO VCO Utput D t _{THL}	ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\label{eq:2.1} \begin{array}{ c c c c } \hline V_{DD} = 15V \\ \hline C1 = 50 \ pF, \ R1 = 10 \ k\Omega, \\ R2 = \infty, \ VCO_{IN} = V_{DD} \\ \hline V_{DD} = 5V \\ \hline V_{DD} = 10V \\ \hline V_{DD} = 15V \\ \hline VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \ge 10 \ k\Omega, \ V_{DD} = 5V \\ \hline VCO_{IN} = 5V \pm 2.5V, \\ R1 \ge 400 \ k\Omega, \ V_{DD} = 10V \\ \hline VCO_{IN} = 7.5V \pm 5V, \\ R1 \ge 1 \ M\Omega, \ V_{DD} = 15V \\ \hline \begin{array}{l} \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ \hline V_{DD} = 5V \\ \hline V_{DD} = 15V \\ \hline \end{array} \end{array}$	0.6	200 0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		MH %
Linearity Linearity Tempera No Fre VCO _{IN} Input Re VCO VCO VCO Utput D t _{THL}	ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\begin{array}{c} C1 = 50 \ p\text{F}, \ R1 = 10 \ \text{k}\Omega, \\ R2 = \infty, VCO_{ N} = V_{DD} \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{ N} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ \text{k}\Omega, \ V_{DD} = 5V \\ VCO_{ N} = 5V \pm 2.5V, \\ R1 \geq 400 \ \text{k}\Omega, \ V_{DD} = 10V \\ VCO_{ N} = 7.5V \pm 5V, \\ R1 \geq 1 \ \text{M}\Omega, \ V_{DD} = 15V \\ \hline \\ \\ \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \hline \\ \\ V_{DD} = 5V \\ V_{DD} = 5V \\ \hline \\ \end{array}$	0.6	0.8 1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		%
Linearity Linearity Tempera No Fre VCO _{IN} Input Re VCO VCO VCO Utput D t _{THL}	ty rature-Frequency Stability requency Offset, f _{MIN} = 0	$\begin{array}{l} R2 = \infty, VCO_{IN} = V_{DD} \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \end{array} \\ \begin{array}{l} VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ \text{k}\Omega, \ V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \ \text{k}\Omega, \ V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ \text{M}\Omega, \ V_{DD} = 15V \\ \end{array} \\ \begin{array}{l} \frac{9}{\sqrt{PC}} < 5c1/f. \ V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \end{array} \\ \begin{array}{l} \frac{9}{\sqrt{PC}} < 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \end{array} \\ \end{array}$	0.6	1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		%
Tempera No Fre Frequent VCO _{IN} Input Re VCO VCO VCO VCO Output D t _{THL}	rature-Frequency Stability requency Offset, f _{MIN} = 0	$\label{eq:second} \begin{array}{l} V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ \text{k}\Omega, \ V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \ \text{k}\Omega, \ V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ \text{M}\Omega, \ V_{DD} = 15V \\ \hline \\ \begin{array}{l} \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ V_{DD} = 15V \\ \hline \end{array} \end{array}$	0.6	1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		%
Tempera No Fre Frequent VCO _{IN} Input Re VCO VCO VCO VCO Output D t _{THL}	rature-Frequency Stability requency Offset, f _{MIN} = 0	$\label{eq:second} \begin{array}{l} V_{DD} = 10V \\ V_{DD} = 15V \\ \hline \\ VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ k\Omega, \ V_{DD} = 5V \\ VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \ k\Omega, \ V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ M\Omega, \ V_{DD} = 15V \\ \hline \\ \begin{array}{l} \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ V_{DD} = 15V \\ \hline \\ V_{DD} = 15V \\ \hline \\ V_{DD} = 5V \\ \hline \end{array} $	0.6	1.2 1.6 1 1 1 0.12–0.24 0.04–0.08		%
Tempera No Fre Frequent VCO _{IN} Input Re VCO VCO VCO VCO Output D t _{THL}	rature-Frequency Stability requency Offset, f _{MIN} = 0	$\label{eq:2.1} \begin{array}{ c c c c } \hline V_{DD} = 15V \\ \hline VCO_{IN} = 2.5V \pm 0.3V, \\ R1 \geq 10 \ \text{k}\Omega, \ V_{DD} = 5V \\ \hline VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \ \text{k}\Omega, \ V_{DD} = 10V \\ \hline VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ \text{M}\Omega, \ V_{DD} = 15V \\ \hline \%''C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ \hline V_{DD} = 5V \\ \hline V_{DD} = 15V \\ \hline V_{DD} = 15V \\ \hline \end{array}$		1.6 1 1 1 0.12–0.24 0.04–0.08		%
Tempera No Fre Frequent VCO _{IN} Input Re VCO VCO VCO VCO Output D t _{THL}	rature-Frequency Stability requency Offset, f _{MIN} = 0	$\label{eq:constraint} \begin{array}{l} VCO_{IN} = 2.5V\pm0.3V, \\ R1 \geq 10 \; k\Omega, \; V_{DD} = 5V \\ VCO_{IN} = 5V\pm2.5V, \\ R1 \geq 400 \; k\Omega, \; V_{DD} = 10V \\ VCO_{IN} = 7.5V\pm5V, \\ R1 \geq 1 \; M\Omega, \; V_{DD} = 15V \\ \\ \hline \\ & \ensuremath{\mathscr{G}}^{*}C < 5c1/f. \; V_{DD} \\ R2 = \infty \\ V_{DD} = 5V \\ \\ & \ensuremath{V}_{DD} = 15V \\ \\ \hline \\ & \ensuremath{V}_{DD} = 15V \\ \\ \hline \\ & \ensuremath{V}_{DD} = 5V \\ \\ \hline \\ & \ensuremath{V}_{DD} = 5V \\ \end{array} $		1 1 1 0.12-0.24 0.04-0.08		
Tempera No Fre Frequent VCO _{IN} Input Re VCO VCO VCO VCO Output D t _{THL}	rature-Frequency Stability requency Offset, f _{MIN} = 0	$ \begin{array}{l} R1 \geq 10 \; k\Omega, \; V_{DD} = 5V \\ VCO_{ N} = 5V \pm 2.5V, \\ R1 \geq 400 \; k\Omega, \; V_{DD} = 10V \\ VCO_{ N} = 7.5V \pm 5V, \\ R1 \geq 1 \; M\Omega, \; V_{DD} = 15V \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$		1 1 0.12-0.24 0.04-0.08		%
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$\label{eq:constraint} \begin{array}{l} VCO_{IN} = 5V \pm 2.5V, \\ R1 \geq 400 \; k\Omega, \; V_{DD} = 10V \\ VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \; M\Omega, \; V_{DD} = 15V \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$		1 1 0.12-0.24 0.04-0.08		
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$ \begin{array}{l} {\sf R1} \geq 400 \; {\sf k}\Omega, \; {\sf V}_{DD} = 10{\sf V} \\ {\sf VCO}_{ {\sf N}} = 7.5{\sf V} \pm 5{\sf V}, \\ {\sf R1} \geq 1\; {\sf M}\Omega, \; {\sf V}_{DD} = 15{\sf V} \\ \\ {}^{\circ}\!$		1 0.12-0.24 0.04-0.08		
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$\label{eq:VCO_IN} \begin{array}{l} VCO_{IN} = 7.5V \pm 5V, \\ R1 \geq 1 \ M\Omega, \ V_{DD} = 15V \\ \\ \end{tabular} \\ \end{tabular} \\ R2 = \infty \\ \end{tabular} \\ \end$		1 0.12-0.24 0.04-0.08		%/°
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$\label{eq:relation} \begin{array}{l} R1 \geq 1 \ M\Omega, \ V_{DD} = 15V \\ \\ \ \%'^{\circ}C < 5c1/f. \ V_{DD} \\ R2 = \infty \\ \\ \ V_{DD} = 5V \\ \\ \ V_{DD} = 10V \\ \\ \ V_{DD} = 15V \\ \\ \end{array} \\ \begin{array}{l} \\ \ V_{DD} = 5V \\ \\ \end{array} \end{array}$		0.12-0.24 0.04-0.08		9/ /0
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$\%^{\circ}C < 5c1/f. V_{DD}$ $R2 = \infty$ $V_{DD} = 5V$ $V_{DD} = 10V$ $V_{DD} = 15V$ $V_{DD} = 5V$		0.12-0.24 0.04-0.08		9/ /0
No Frequence VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	requency Offset, f _{MIN} = 0	$R2 = \infty$ $V_{DD} = 5V$ $V_{DD} = 10V$ $V_{DD} = 15V$ $V_{DD} = 5V$		0.04-0.08		0/ /0
Frequent VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D		$V_{DD} = 5V$ $V_{DD} = 10V$ $V_{DD} = 15V$ $V_{DD} = 5V$		0.04-0.08		0 / /0
VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	ncy Offset, f _{MIN} ≠ 0	$V_{DD} = 10V$ $V_{DD} = 15V$ $V_{DD} = 5V$		0.04-0.08		0/ /0
VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	ncy Offset, f _{MIN} ≠ 0	$V_{DD} = 15V$ $V_{DD} = 5V$				0//0
VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	ncy Offset, f _{MIN} ≠ 0	$V_{DD} = 5V$		0 015-0 03		-70/
VCO _{IN} Input Re VCO Output D t _{THL} VCO Output D	ncy Offset, f _{MIN} ≠ 0	= =				
VCO Output E		$V_{DD} = 10V$		0.06-0.12		
VCO Output E t _{THL} VCO Output E				0.05-0.1		%/°
VCO Output E t _{THL} VCO Output E		$V_{DD} = 15V$		0.03-0.06		
t _{THL} VCO Ou	esistance	$V_{DD} = 5V$		10 ⁶		
t _{THL} VCO Ou		$V_{DD} = 10V$		10 ⁶ 10 ⁶		۵M
t _{THL} VCO Ou	Duty Cyclo	$V_{DD} = 15V$		50		
		$V_{DD} = 5V$		50 50		%
		$V_{DD} = 10V$		50		70
	utput Transition Time	$V_{DD} = 15V$ $V_{DD} = 5V$		90	200	ns
THL		$V_{DD} = 3V$ $V_{DD} = 10V$		50	100	113
		$V_{DD} = 15V$		45	80	ns
PHASE COMPARATO	TORS SECTION	*DD = 10 V		40	00	
	esistance		1	Т		1
	al Input	$V_{DD} = 5V$	1	3		
0		$V_{DD} = 10V$	0.2	0.7		
		V _{DD} = 15V	0.1	0.3		
Compa	parator Input	$V_{DD} = 5V$		10 ⁶		۵M
		$V_{DD} = 10V$		10 ⁶		
		V _{DD} = 15V		10 ⁶		
	upled Signal Input Voltage	C _{SERIES} = 1000 pF				1
Sensitivi	vity	f = 50 kHz				
		$V_{DD} = 5V$		200	400	
		$V_{DD} = 10V$		400	800	m\
				700	1400	
DEMODULATOR OU		$V_{DD} = 15V$				

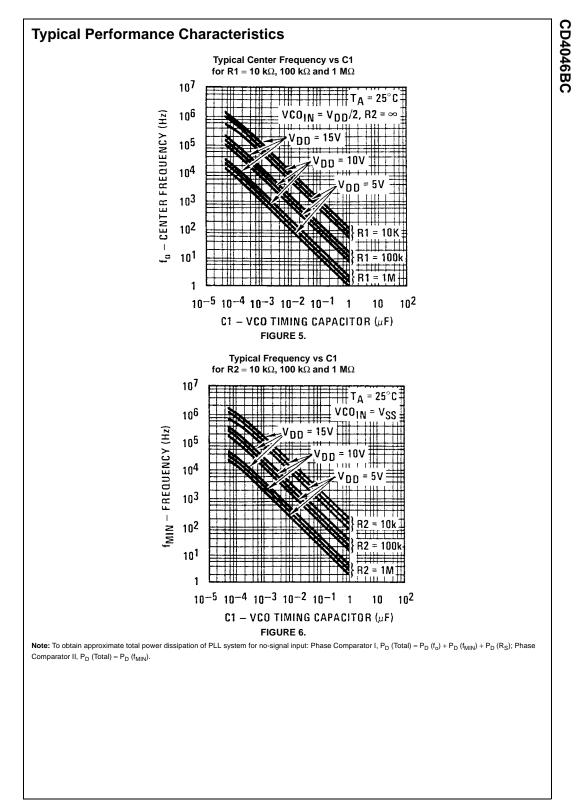
Symbol	Parameter	Conditions	Min	Тур	Max	Units
VCO _{IN} -	Offset Voltage	$RS \ge 10 \ k\Omega, \ V_{DD} = 5V$		1.50	2.2	
V _{DEM}		$RS \ge 10 \ k\Omega, \ V_{DD} = 10V$		1.50	2.2	V
		$RS \ge 50 \ k\Omega, \ V_{DD} = 15V$		1.50	2.2	
	Linearity	$RS \ge 50 \ k\Omega$				
		VCO_{IN} = 2.5V \pm 0.3V, V_{DD} = 5V		0.1		
		$VCO_{IN}=5V\pm2.5V,\ V_{DD}=10V$		0.6		%
		$VCO_{IN}=7.5V\pm5V,V_{DD}=15V$		0.8		
ZENER DI	DDE					
VZ	Zener Diode Voltage	I _Z = 50 μA	6.3	7.0	7.7	V
R ₇	Zener Dynamic Resistance	$I_Z = 1 \text{ mA}$		100		Ω

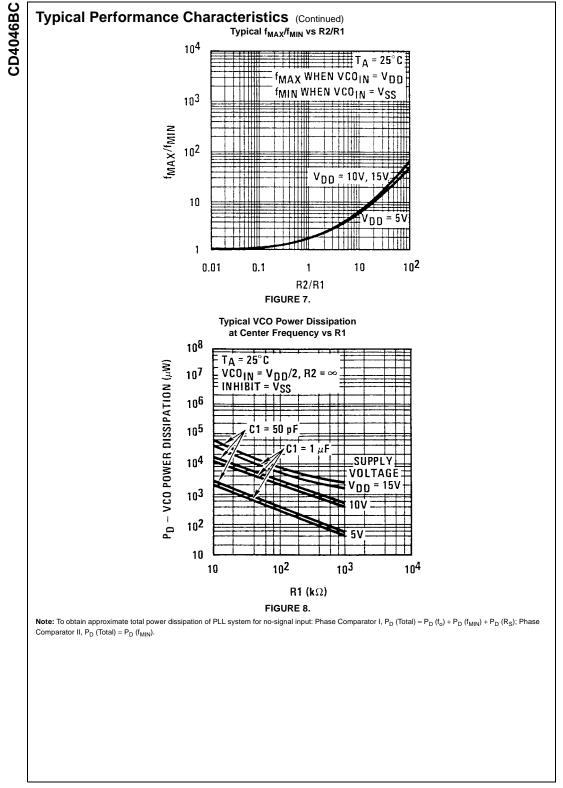
Phase Comparator State Diagrams



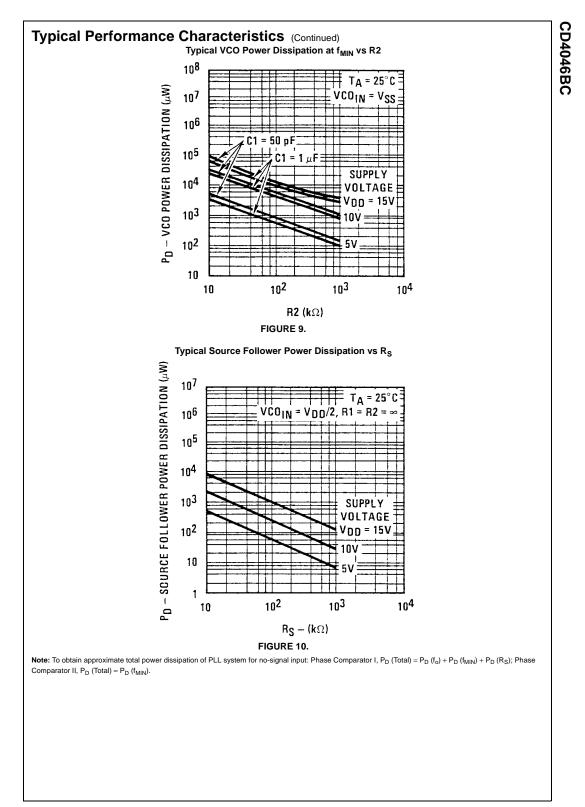


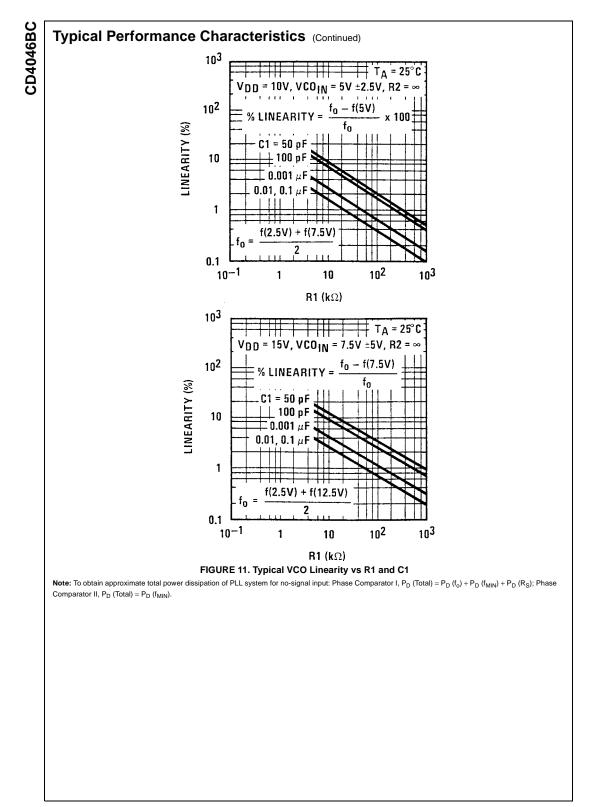






8





Design Information

This information is a guide for approximating the value of external components for the CD4046B in a phase-locked-loop system. The selected external components must be within the following ranges: R1, R2 \geq 10 kΩ, R_S \geq 10 kΩ, C1 \geq 50 pF.

In addition to the given design information, refer to Figure 5, Figure 6, Figure 7 for R1, R2 and C1 component selections.

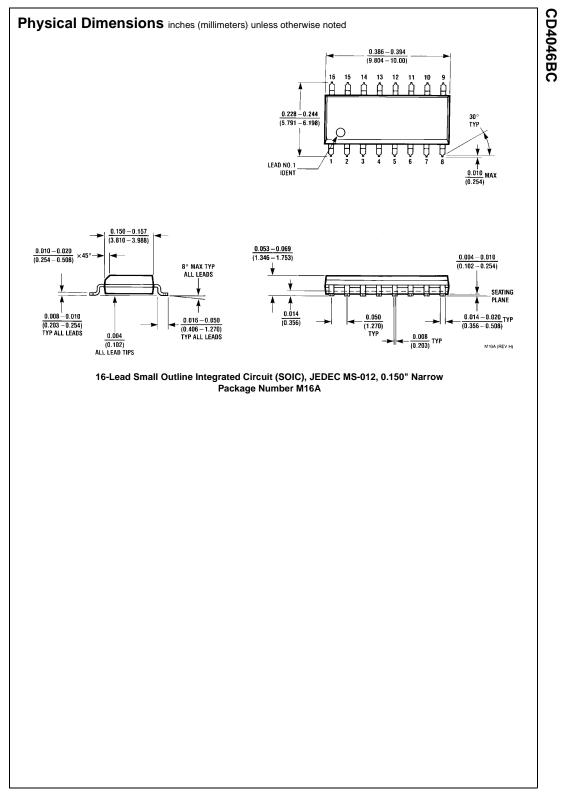
CD4046BC

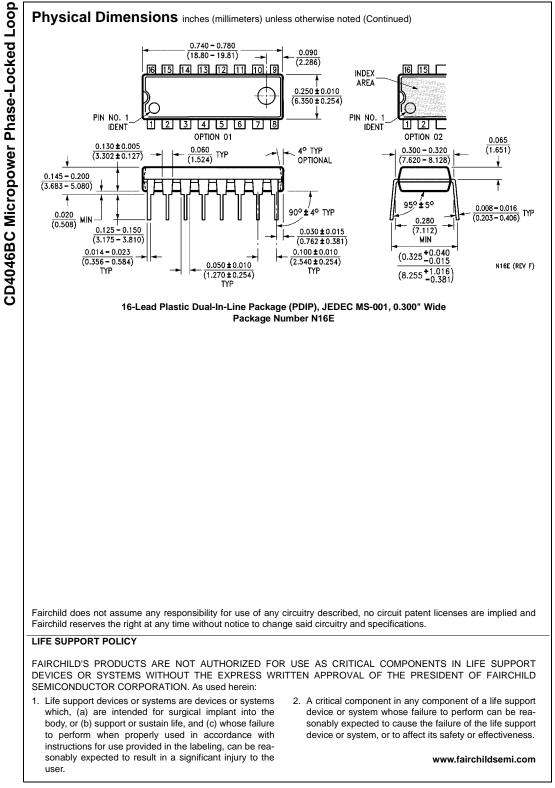
Using Phase	Comparator I	Using Phase Comparator II			
VCO Without Offset VCO With Offset		VCO Without Offset	VCO With Offset		
R2 = ∞		R2 = ∞			
MAX 10 10 10 10 10 10 10 10 10 10	WAX to fMIN VDD/2 VDD VCD INPUT VOLTAGE	Чмах г., ным <u>VpD/2</u> VpD VCD INPUT VDL TAGE	Гмах Го Типи VDD/2 VDD		
VCO in PLL sy	stem will adjust	VCO in PLL system will adjust to			
to center fr			g frequency, f _{min}		
	nax - f _{min}				
	$2\mathrm{f_C}\approx\frac{1}{\pi}\sqrt{\frac{2\pi\mathrm{f_L}}{\tau\mathrm{1}}}$				
	For 2 f _C , see Ref.	f _C :	= f _L		
90° at center frequen	cy (f _o), approximating	Always (0° in lock		
0° and 180° at ends	s of lock range (2 f _L)				
Ye	es	N	lo		
Hi	gh	Lo	W		
<u></u>					
	VCO Without Offset R2 = ∞ ¹ MAX ¹ O ¹	$R2 = \infty$ I_{MAX} I_{0} I	VCO Without Offset R2 = ∞ VCO With Offset R2 = ∞ VCO Without Offset R2 = ∞ Image: transmit of the transmit of transmit		

	Using Phase	e Comparator I	Using Phase Comparator II		
Characteristics	VCO Without Offset	VCO With Offset	VCO Without Offset	VCO With Offs	
	R2 = ∞		R2 = ∞		
VCO Component	Given: fo.	Given: fo and fL.	Given: f _{max} .	Given: fmin and fma	
Selection	Use f _o with	Calculate f _{min}	Calculate fo from	Use f _{min} with	
	Figure 5 to	from the equation	the equation	Figure 6 to	
	determine R1 and C1.	$f_{min} = f_o - f_L.$	$f_0 = \frac{f_{max}}{2}$.	to determine R2 an C1.	
		Use f _{min} with Figure 6 to		Calculate	
		determine R2 and C1.		f _{max} f _{min}	
			Use fo with Figure 5 to		
		Calculate	determine R1 and C1.	Use	
		f _{max}		f _{max}	
		f _{min}		f _{min} with Figure 7	
		from the equation		to determine ratio	
		$\frac{f_{max}}{f_{min}} = \frac{f_0 + f_L}{f_0 - f_L}.$		R2/R1 to obtain R1	
		Use			
		f _{max} f _{min} with Figure 7			
		to determine ratio R2/			

References

G.S. Moschytz, "Miniaturized RC Filters Using Phase-Locked Loop", BSTJ, May, 1965. Floyd Gardner, "Phaselock Techniques", John Wiley & Sons, 1966.







OUR CERTIFICATE

DiGi provide top-quality products and perfect service for customer worldwide through standardization, technological innovation and continuous improvement. DiGi through third-party certification, we striciy control the quality of products and services. Welcome your RFQ to Email: Info@DiGi-Electronics.com

	<section-header></section-header>		
Marchine Marchine Marchine M	Market	Marchine Marchine Image: Control of the sector of the sec	





Tel: +00 852-30501935

RFQ Email: Info@DiGi-Electronics.com

DiGi is a global authorized distributor of electronic components.